

Multilevel adaptivity for stochastic finite element methods

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Irish Numerical Analysis Forum

26 January 2021

EPSRC

Engineering and Physical Sciences
Research Council



**UNIVERSITY OF
BIRMINGHAM**

What is this talk about...

- * Computational methods for uncertainty quantification (UQ)
 - ▶ PDEs with uncertain or parameter-dependent inputs
 - ▶ forward UQ: propagation of uncertainty from the inputs/data to the output/solution
 - ▶ approximations of the input-output map
- * Numerical solution of elliptic PDE problems with parametric or uncertain inputs using
 - ▶ stochastic Galerkin FEM
 - ▶ stochastic collocation FEM
- * Design and analysis of adaptive algorithms
 - ▶ focus on multilevel adaptivity

Parametric model problem

Problem formulation: find $u : D \times \Gamma \rightarrow \mathbb{R}$ satisfying

$$\begin{aligned} -\nabla_x \cdot (a(x, \mathbf{y}) \nabla_x u(x, \mathbf{y})) &= f(x) & x \in D, \mathbf{y} \in \Gamma, \\ u(x, \mathbf{y}) &= 0 & x \in \partial D, \mathbf{y} \in \Gamma \end{aligned}$$

■ Domains

- ▶ $D \subset \mathbb{R}^2 \rightsquigarrow$ physical domain
- ▶ $\Gamma := [-1, 1]^N$ or $\Gamma := [-1, 1]^M \rightsquigarrow$ parameter domain

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Remark: parameters y_1, y_2, \dots can be seen as images (observations) of independent real-valued random variables with cumulative distribution functions $\pi_1(y_1), \pi_2(y_2), \dots$. Then, the joint cumulative distribution function is defined as

$$\pi(\mathbf{y}) := \prod_{m=1}^{\infty} \pi_m(y_m), \quad \text{and} \quad \int_{-1}^1 d\pi_m(y_m) = \int_{\Gamma} d\pi(\mathbf{y}) = 1.$$

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■ Challenges for numerics (and analysis)

- ▶ high-dimensional parameter domain \rightsquigarrow ‘curse of dimensionality’
- ▶ guaranteed and reliable error control in approximations (*rigorous a posteriori error analysis*)
- ▶ tuning of spatial and stochastic components of approximations
- ▶ adaptive algorithms that are *provably convergent with optimal rates*

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 - ▶ effective and dimension independent
 - ▶ estimating the moments of the solution

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Parametric model problem... and numerical solution methods

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- ▶ candidates for Ψ_n : orthogonal polynomials, Lagrange basis functions, ...

Parametric model problem: affine-parametric coefficient (1/2)

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■ Affine-parametric diffusion coefficient

- ▶ $\Gamma := [-1, 1]^N \rightsquigarrow$ parameter domain
- ▶ $a(x, \mathbf{y}) = a_0(x) + \sum_{m \in \mathbb{N}} y_m a_m(x)$ for $x \in D$, $\mathbf{y} = (y_m)_{m \in \mathbb{N}} \in \Gamma$
- ▶ $0 < a_0^{\min} \leq a_0(x) \leq a_0^{\max} < \infty$ for almost all $x \in D$
- ▶ $\tau := \frac{1}{a_0^{\min}} \left\| \sum_{m \in \mathbb{N}} |a_m| \right\|_{L^\infty(D)} < 1$ & $\sum_{m \in \mathbb{N}} \|a_m\|_{L^\infty(D)} < \infty$

Remark: $a_0(x)$ typically represents the mean field, i.e., $a_0(x) = \int_\Gamma a(x, \mathbf{y}) d\pi(\mathbf{y})$.

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■ $\mathbb{X} := H_0^1(D)$, $\mathbb{P} := L_\pi^2(\Gamma)$, $\pi(\mathbf{y}) = \prod_{m \in \mathbb{N}} \pi_m(y_m)$; $\mathbb{V} := L_\pi^2(\Gamma; \mathbb{X}) \cong \mathbb{X} \otimes \mathbb{P}$

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- Bilinear forms on \mathbb{V}

- ▶ $B_0(u, v) := \int_\Gamma \int_D a_0(x) \nabla u(x, \mathbf{y}) \cdot \nabla v(x, \mathbf{y}) \, dx \, d\pi(\mathbf{y})$

- ▶ $B(u, v) := B_0(u, v) + \sum_{m \in \mathbb{N}} \int_\Gamma y_m \int_D a_m(x) \nabla u(x, \mathbf{y}) \cdot \nabla v(x, \mathbf{y}) \, dx \, d\pi(\mathbf{y})$

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Weak formulation: given $f \in L^2(D)$, find $u \in \mathbb{V}$ such that

$$B(u, v) = F(v) := \int_\Gamma \int_D f(x) v(x, \mathbf{y}) \, dx \, d\pi(\mathbf{y}) \quad \text{for all } v \in \mathbb{V} \quad (*)$$

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[Schwab, Gittelsohn '11]: the assumptions on $a(x, \mathbf{y})$ ensure the wellposedness of (*).

Stochastic Galerkin FEM (1/2)

- Finite dimensional subspace

$$\mathbb{V}_\bullet \subset \mathbb{V} \cong \mathbb{X} \otimes \mathbb{P}$$

Galerkin projection:

find $u_\bullet \in \mathbb{V}_\bullet$ such that $B(u_\bullet, v_\bullet) = F(v_\bullet)$ for all $v \in \mathbb{V}_\bullet$.

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- Galerkin orthogonality

$$B(u - u_\bullet, v_\bullet) = 0 \text{ for all } v_\bullet \in \mathbb{V}_\bullet.$$

- Best approximation property

$$\| \| u - u_\bullet \| \| = \min_{v_\bullet \in \mathbb{V}_\bullet} \| \| u - v_\bullet \| \|, \text{ where } \| \| \cdot \| \| := B(\cdot, \cdot)^{1/2}$$

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- **Main question:** how to choose \mathbb{V}_\bullet ?

Stochastic Galerkin FEM (2/2)

- $\{P_\nu : \nu \in \mathcal{J}\}$ is a countable orthonormal polynomial basis of $\mathbb{P} = L^2_\pi(\Gamma)$
- gPC expansion: $\forall \exists u(x, \mathbf{y}) = \sum_{\nu \in \mathcal{J}} u_\nu(x) P_\nu(\mathbf{y})$ with unique $u_\nu \in \mathbb{X} = H^1_0(D)$

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Example

$$\nu = (2, 5, 0, 3, 0, 0, 0, \dots) \rightsquigarrow \text{supp}(\nu) = \{1, 2, 4\}$$

$$\rightsquigarrow P_\nu(\mathbf{y}) = P_2(y_1) P_5(y_2) P_3(y_4)$$

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- Discretisation in the **parameter** domain
 - ▶ finite index set $\mathcal{P}_\bullet \subset \mathcal{J} \implies \mathbb{P}_\bullet = \text{span}\{P_\nu : \nu \in \mathcal{P}_\bullet\} \subset \mathbb{P} = L^2_\pi(\Gamma)$
 - ▶ semidiscrete approximation via truncation of gPC expansion

$$u(x, \mathbf{y}) \approx \sum_{\nu \in \mathcal{P}_\bullet} u_\nu(x) P_\nu(\mathbf{y}) \in \mathbb{X} \otimes \mathbb{P}_\bullet \text{ with coefficients } u_\nu \in \mathbb{X} = H^1_0(D)$$

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- Discretisations in the **physical** domain

- ▶ A sequence of meshes $\rightsquigarrow \{\mathcal{T}_{\bullet, \nu}\}_{\nu \in \mathcal{P}_\bullet}$
- ▶ $u_\bullet(x, \mathbf{y}) = \sum_{\nu \in \mathcal{P}_\bullet} u_{\bullet, \nu}(x) P_\nu(\mathbf{y})$ with $u_{\bullet, \nu} \in \mathbb{X}_{\bullet, \nu} = \mathcal{S}_0^1(\mathcal{T}_{\bullet, \nu})$ for all $\nu \in \mathcal{P}_\bullet$

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- $\mathbb{V}_\bullet := \bigoplus_{\nu \in \mathcal{P}_\bullet} [\mathbb{X}_{\bullet\nu} \otimes \text{span}\{P_\nu\}]$, $\dim \mathbb{V}_\bullet = \sum_{\nu \in \mathcal{P}_\bullet} \dim \mathbb{X}_{\bullet\nu}$ (**multilevel SGFEM**)

Hierarchical a posteriori error estimators: main ideas

- Pythagoras theorem: $u \in \mathbb{V}$, $u_\bullet \in \mathbb{V}_\bullet \subset \mathbb{V}$, $\hat{u}_\bullet \in \hat{\mathbb{V}}_\bullet \supset \mathbb{V}_\bullet$ (enhanced approx.)

$$\| \| u - u_\bullet \| \|^2 = \| \| (u - \hat{u}_\bullet) + (\hat{u}_\bullet - u_\bullet) \| \|^2 = \| \| u - \hat{u}_\bullet \| \|^2 + \underbrace{\| \| \hat{u}_\bullet - u_\bullet \| \|^2}_{\text{computable}}$$

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- Saturation assumption: $\exists q_{\text{sat}} \in (0, 1)$ such that $\| \| u - \hat{u}_\bullet \| \leq q_{\text{sat}} \| \| u - u_\bullet \|$

Hierarchical a posteriori error estimators: main ideas

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$$\| \| u - u_\bullet \| \|^2 = \| \| (u - \hat{u}_\bullet) + (\hat{u}_\bullet - u_\bullet) \| \|^2 = \| \| u - \hat{u}_\bullet \| \|^2 + \underbrace{\| \| \hat{u}_\bullet - u_\bullet \| \|^2}_{\text{computable}}$$

$$\implies \| \| u - u_\bullet \| \geq \| \| \hat{u}_\bullet - u_\bullet \| \quad (\text{efficiency})$$

- Saturation assumption: $\exists q_{\text{sat}} \in (0, 1)$ such that $\| \| u - \hat{u}_\bullet \| \leq q_{\text{sat}} \| \| u - u_\bullet \| \|^2$

- Pythagoras theorem & saturation assumption imply that

$$\| \| u - u_\bullet \| \leq (1 - q_{\text{sat}}^2)^{-1/2} \| \| \hat{u}_\bullet - u_\bullet \| \quad (\text{reliability})$$

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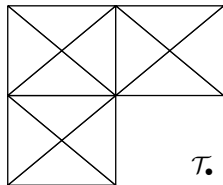
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- [Bank, Weiser '85]: decomposition $\hat{\mathbb{V}}_\bullet = \mathbb{V}_\bullet \oplus \mathbb{W}_\bullet$

\implies hierarchical error estimation without computing enhanced approximations \hat{u}_\bullet

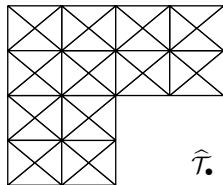
Enhancement of SGFEM approximations (1/2)

- Enhancement of approximations in **physical** domain
 - ▶ initial mesh \mathcal{T}_0
 - ▶ add new vertices to \mathcal{T}_\bullet \rightsquigarrow mesh refinement
 - ▶ mesh refinement by newest vertex bisection (NVB)
 - ▶ $\hat{\mathcal{T}}_\bullet$ \rightsquigarrow uniform refinement of \mathcal{T}_\bullet



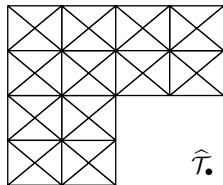
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- Enhancement of approximations in the **parameter** domain
 - ▶ add new indices to \mathcal{P}_\bullet
 - ▶ finite set $\mathcal{Q}_\bullet \subset \mathcal{J} \setminus \mathcal{P}_\bullet \rightsquigarrow$ detail index set ('boundary' of \mathcal{P}_\bullet)
 - ▶ $\hat{\mathcal{P}}_\bullet = \mathcal{P}_\bullet \cup \mathcal{Q}_\bullet \rightsquigarrow$ uniform enrichment of \mathcal{P}_\bullet
 - ▶ $\hat{\mathbb{P}}_\bullet = \text{span}\{P_\nu : \nu \in \hat{\mathcal{P}}_\bullet\} \supset \mathbb{P}_\bullet$

Example

- ▶ $\mathcal{P}_\bullet = \{(0, 0, \dots); (1, 0, \dots); (0, 1, 0, \dots)\}$
 $\implies \mathcal{Q}_\bullet = \{(2, 0, \dots); (1, 1, 0, \dots); (0, 2, 0, \dots); (0, 0, 1, 0, \dots)\}$

Enhancement of SGFEM approximation (2/2)

- Two sources of error: $\| \| u - u_{\bullet} \| \| ^2 = (\mathbb{X}\text{-errors})^2 + (\mathbb{P}\text{-error})^2$

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[B., Praetorius, Ruggeri; SIAM/ASA JUQ '21]

$$\widehat{\mathbb{V}}_\bullet = \underbrace{\bigoplus_{\nu \in \mathcal{P}_\bullet} [\widehat{\mathbb{X}}_{\bullet,\nu} \otimes \text{span}\{P_\nu\}]}_{\text{spatial enhancement}} \oplus \underbrace{\bigoplus_{\nu \in \mathcal{Q}_\bullet} [\mathbb{X}_0 \otimes \text{span}\{P_\nu\}]}_{\text{parametric enhancement}}$$

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- Recap: $\| \| u - u_\bullet \| \|^2 \simeq \| \| \widehat{u}_\bullet - u_\bullet \| \|^2$, but we want to avoid computing $\widehat{u}_\bullet \in \widehat{\mathbb{V}}_\bullet$!

A posteriori error estimation: spatial and parametric estimators

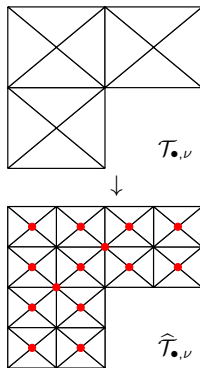
■ Two-level **spatial** error estimator

[Mund, Stephan, Weiße '98], [Mund, Stephan '99]

- ▶ Fix a multiindex $\nu \in \mathcal{P}_\bullet$.
- ▶ $\mathcal{N}_{\bullet,\nu}^+ \rightsquigarrow$ set of interior midpoints in $\mathcal{T}_{\bullet,\nu}$
- ▶ $\hat{\varphi}_{\bullet,\nu,z} \in \hat{\mathbb{X}}_{\bullet,\nu} \rightsquigarrow$ hat function associated with $z \in \mathcal{N}_{\bullet,\nu}^+$

$$\eta_{\bullet}^2(\nu, z) = \frac{|F(\hat{\varphi}_{\bullet,\nu,z} P_\nu) - B(u_\bullet, \hat{\varphi}_{\bullet,\nu,z} P_\nu)|^2}{\|a_0^{1/2} \nabla \hat{\varphi}_{\bullet,\nu,z}\|_{L^2(D)}^2}$$

$$\langle \mathbb{X}\text{-errors} \rangle^2 \approx \sum_{\nu \in \mathcal{P}_\bullet} \sum_{z \in \mathcal{N}_{\bullet,\nu}^+} \eta_{\bullet}^2(\nu, z)$$



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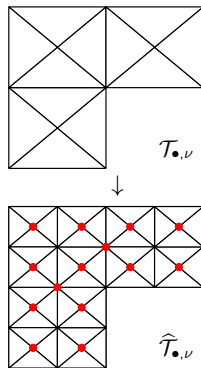
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$$(\mathbb{X}\text{-errors})^2 \approx \sum_{\nu \in \mathcal{P}} \sum_{z \in \mathcal{N}_{\bullet,\nu}^+} \eta_{\bullet}^2(\nu, z)$$

■ Hierarchical **parametric** error estimator

[B., Silvester '16], [B., Praetorius, Ruggeri; SIAM/ASA JUQ '21]

- ▶
$$(\mathbb{P}\text{-error})^2 \approx \sum_{\nu \in \mathcal{Q}_{\bullet}} \eta_{\bullet}^2(\nu)$$



A posteriori error estimation: main results

[B., Praetorius, Ruggeri; SIAM/ASA JUQ '21]

$$\blacksquare \eta_{\bullet}^2 = (\text{estim. } \mathbb{X}\text{-errors})^2 + (\text{estim. } \mathbb{P}\text{-error})^2 = \sum_{\nu \in \mathcal{P}_{\bullet}} \sum_{z \in \mathcal{N}_{\bullet, \nu}^+} \eta_{\bullet}^2(\nu, z) + \sum_{\nu \in \mathcal{Q}_{\bullet}} \eta_{\bullet}^2(\nu)$$

Theorem 1 (equivalence of total error estimate and error reduction)

There exists $C = C(a_0, \tau, \mathcal{T}_0) \geq 1$ such that

$$C^{-1} \eta_{\bullet}^2 \leq \| \hat{u}_{\bullet} - u_{\bullet} \|^2 \leq C \eta_{\bullet}^2$$

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Corollary (efficiency & reliability)

$$\blacksquare \|\| u - u_{\bullet} \|\|^2 \geq C^{-1} \eta_{\bullet}^2 \quad (\text{efficiency})$$

$$\blacksquare \text{saturation assumption} \implies \|\| u - u_{\bullet} \|\|^2 \leq \frac{C}{1 - q_{\text{sat}}^2} \eta_{\bullet}^2 \quad (\text{reliability})$$

A posteriori error estimation: main results

[B., Praetorius, Ruggeri; SIAM/ASA JUQ '21]

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Remark

- ▶ $\eta_{\bullet}(\nu, z)$ is associated with an interior edge midpoint $z \in \mathcal{N}_{\bullet, \nu}^+$ for each $\nu \in \mathcal{P}_{\bullet}$.
- ▶ $\eta_{\bullet}(\nu)$ is associated with a new index $\nu \in \mathcal{Q}_{\bullet}$.

These are local *error reduction indicators* for
spatial refinement / parametric enrichment \implies key to adaptivity

Adaptive SGFEM algorithm

INPUT: initial mesh \mathcal{T}_0 , initial index set $\mathcal{P}_0 = \{(0, 0, \dots)\}$, tolerance tol

FOR $\ell = 0, 1, 2, 3, \dots$ DO:

- SOLVE: compute $u_\ell \in \mathbb{V}_\ell$ for index set \mathcal{P}_ℓ and meshes $\mathcal{T}_{\ell,\nu}$ ($\nu \in \mathcal{P}_\ell$)
- ESTIMATE: compute *local* error indicators and the *total* error estimate
 - ▶ spatial & parametric indicators
 $\{\eta_\ell(\nu, z); z \in \mathcal{N}_{\ell,\nu}^+, \nu \in \mathcal{P}_\ell\}$ & $\{\eta_\ell(\nu); \nu \in \mathcal{Q}_\ell\}$
 - ▶ energy error estimate η_ℓ
 - ▶ IF $\eta_\ell < \text{tol}$ THEN STOP
- MARK: mark certain vertices $\mathcal{M}_{\ell,\nu} \subseteq \mathcal{N}_{\ell,\nu}^+$ ($\nu \in \mathcal{P}_\ell$) and indices $\mathcal{R}_\ell \subseteq \mathcal{Q}_\ell$
- REFINE: enhance approximation space
 - ▶ mesh refinement (NVB) $\rightsquigarrow \mathcal{T}_{\ell+1,\nu} = \text{refine}(\mathcal{T}_{\ell,\nu}, \mathcal{M}_{\ell,\nu}) \quad \forall \nu \in \mathcal{P}_\ell$
 - ▶ parametric enrichment $\rightsquigarrow \mathcal{P}_{\ell+1} = \mathcal{P}_\ell \cup \mathcal{R}_\ell, \quad \mathcal{T}_{\ell,\nu} = \mathcal{T}_0 \quad \forall \nu \in \mathcal{R}_\ell$

OUTPUT: stochastic Galerkin approximations $\{u_\ell\}$ and error estimates $\{\eta_\ell\}$

Convergence results

[B., Praetorius, Rocchi, Ruggeri; SINUM '19]

[B., Praetorius, Ruggeri; arXiv preprint '22]

Theorem 2 (plain convergence)

For any marking threshold $\theta \in (0, 1]$ (in Dörfler marking), adaptive multilevel SGFEM algorithm yields a convergent sequence of error estimates, i.e., $\eta_\ell \rightarrow 0$ as $\ell \rightarrow \infty$.

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Theorem 3 (linear convergence)

For any marking threshold $\theta \in (0, 1]$, saturation assumption \implies linear convergence

$$\exists q \in (0, 1) \text{ such that } \|\| u - u_{\ell+1} \|\| \leq q \|\| u - u_\ell \|\| \quad \text{for all } \ell \in \mathbb{N}_0$$

Experiment 1: cookie problem

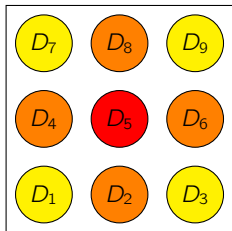
- $-\nabla \cdot (a \nabla u) = f$ in $D \times \Gamma$, $u = 0$ on $\partial D \times \Gamma$
- $a(x, \mathbf{y}) = a_0(x) + \sum_{m \in \mathbb{N}} y_m a_m(x)$
- $D = (0, 1)^2 \rightsquigarrow$ square domain
 - ▶ nine circular inclusions $D_m \subset D$ ($m = 1, \dots, 9$)

- Expansion coefficients $\{a_m\}_{m \in \mathbb{N}_0}$

- ▶ $a_0 \equiv 1$
- ▶ $a_m = 0.5 \chi_{D_m}$ for $m = 1, 3, 7, 9$
- ▶ $a_m = 0.7 \chi_{D_m}$ for $m = 2, 4, 6, 8$
- ▶ $a_m = 0.9 \chi_{D_m}$ for $m = 5$
- ▶ $a_m \equiv 0$ for $m > 9$

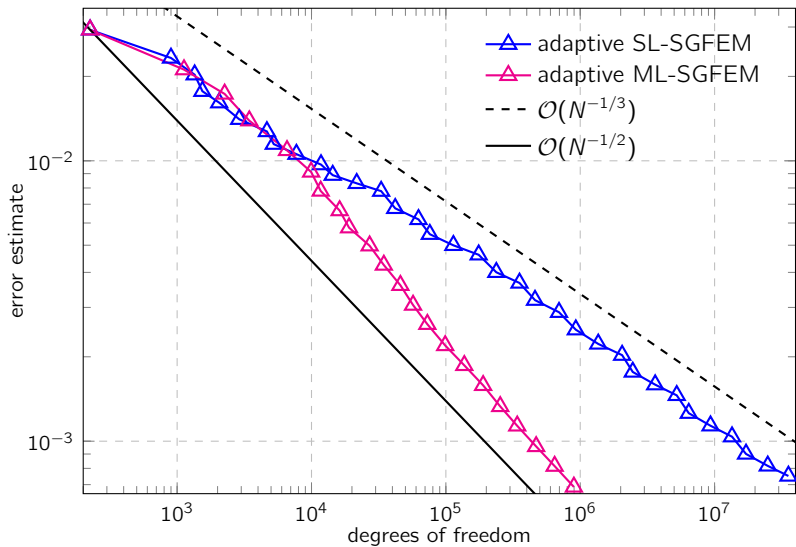
- $f \equiv 1$

- $d\pi_m(y_m) = \frac{1}{2} dy_m \rightsquigarrow$ uniform probability measure on $[-1, 1]$

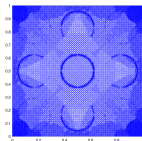
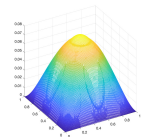


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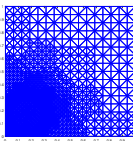
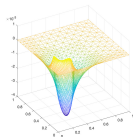
Experiment 1: rate optimality of adaptive ML-SGFEM



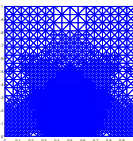
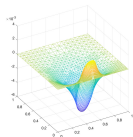
Experiment 1: locally refined meshes in ML-SGFEM



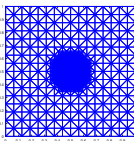
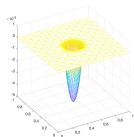
$\nu = (00 \dots 0)$
 $\#\mathcal{T}_{\ell, \nu} = 84050$



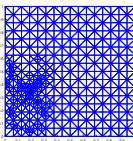
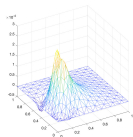
$\nu = (10 \dots 0)$
 $\#\mathcal{T}_{\ell, \nu} = 10994$



$\nu = (010 \dots 0)$
 $\#\mathcal{T}_{\ell, \nu} = 16420$



$\nu = (000010 \dots 0)$
 $\#\mathcal{T}_{\ell, \nu} = 9528$



$\nu = (10010 \dots 0)$
 $\#\mathcal{T}_{\ell, \nu} = 839$

Optimal convergence of adaptive multilevel SGFEM

[B., Praetorius, Ruggeri; IMA J. Numer. Anal. '22]

- Concept of 'multilevel structure' $\rightsquigarrow \mathbf{P}_\bullet = [\mathcal{P}_\bullet, (\mathcal{T}_{\bullet,\nu})_{\nu \in \mathcal{P}_\bullet}]$, $\#\mathcal{P}_\bullet \simeq \dim \mathbb{V}_\bullet$
- Concept of 'multilevel refinement' $\rightsquigarrow \mathbf{P}_\circ = \text{REFINE}(\mathbf{P}_\bullet, \mathbf{M}_\bullet)$
- Concept of optimality \rightsquigarrow approximation class \mathbb{A}_s ($s > 0$)

$$u \in \mathbb{A}_s \iff \exists \{\mathbf{P}_\ell^*\}_{\ell \in \mathbb{N}_0} \text{ such that } \| \| u - u_\ell^* \| \| = \mathcal{O}((\dim \mathbb{V}_\ell^*)^{-s})$$

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Theorem 4 (rate optimality of adaptive multilevel SGFEM)

For sufficiently small marking threshold θ , strong saturation assumption \implies optimal convergence

If $s > 0$ and $u \in \mathbb{A}_s$, then $\sup_{\ell \in \mathbb{N}_0} (\#\mathbf{P}_\ell - \#\mathbf{P}_0 + 1)^s \| \| u - u_\ell \| \| \leq C \| \| u \| \|_{\mathbb{A}_s}$

Saturation assumption vs. strong saturation assumption

- Saturation assumption
 - ▶ SGFEM solution $u_{\bullet} \in \mathbb{V}_{\bullet}$.
 - ▶ Enhanced ('uniformly refined') SGFEM solution $\hat{u}_{\bullet} \in \hat{\mathbb{V}}_{\bullet}$.
 - ▶ There exist a constant $q_{\text{sat}} \in (0, 1)$ s.t. $\| \| u - \hat{u}_{\bullet} \| \| \leq q_{\text{sat}} \| \| u - u_{\bullet} \| \|$

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- Strong saturation assumption
 - ▶ $\mathbb{P}_\bullet \in \text{REFINE}(\mathbb{P}_0) \rightsquigarrow$ any multilevel structure obtained from \mathbb{P}_0
 - ▶ $\mathbb{P}_\star \in \text{REFINE}(\mathbb{P}_\bullet) \rightsquigarrow$ a refined multilevel structure obtained from \mathbb{P}_\bullet
 - ▶ $\mathbb{P}_\circ := \text{REFINE}(\mathbb{P}_\bullet, M_\bullet) \rightsquigarrow$ a multilevel structure obtained from \mathbb{P}_\bullet by **one step of multilevel refinement** towards \mathbb{P}_\star
 - ▶ There exist constants $\exists 0 < \kappa_{\text{sat}} \leq q_{\text{sat}} < 1$ such that

$$\| \| u - u_\star \| \| \leq \kappa_{\text{sat}} \| \| u - u_\bullet \| \| \implies \| \| u - u_\circ \| \| \leq q_{\text{sat}} \| \| u - u_\bullet \| \|$$

Parametric model problem revisited

Problem formulation: find $u : D \times \Gamma \rightarrow \mathbb{R}$ satisfying

$$\begin{aligned} -\nabla_x \cdot (a(x, \mathbf{y}) \nabla_x u(x, \mathbf{y})) &= f(x, \mathbf{y}) & x \in D, \mathbf{y} \in \Gamma, \\ u(x, \mathbf{y}) &= 0 & x \in \partial D, \mathbf{y} \in \Gamma \end{aligned}$$

■ Parametric diffusion coefficient

- ▶ $\Gamma := [-1, 1]^M \rightsquigarrow$ parameter domain, $M \in \mathbb{N}$
- ▶ $0 < a_{\min} \leq \operatorname{ess\,inf}_{x \in D} a(x, \mathbf{y}) \leq \operatorname{ess\,sup}_{x \in D} a(x, \mathbf{y}) \leq a_{\max} < \infty$ π -a.e. on Γ

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- Weak formulation: given $f \in L^2_\pi(\Gamma, L^2(D))$, find $u : \Gamma \rightarrow \mathbb{X} := H_0^1(D)$ s.t.

$$\int_D a(x, \mathbf{y}) \nabla u(x, \mathbf{y}) \cdot \nabla v(x) \, dx = \int_D f(x, \mathbf{y}) v(x) \, dx \quad \forall v \in \mathbb{X}, \pi\text{-a.e. on } \Gamma.$$

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Problem formulation: find $u : D \times \Gamma \rightarrow \mathbb{R}$ satisfying

$$\begin{aligned} -\nabla_x \cdot (a(x, \mathbf{y}) \nabla_x u(x, \mathbf{y})) &= f(x, \mathbf{y}) & x \in D, \mathbf{y} \in \Gamma, \\ u(x, \mathbf{y}) &= 0 & x \in \partial D, \mathbf{y} \in \Gamma \end{aligned}$$

- Parametric diffusion coefficient

- ▶ $\Gamma := [-1, 1]^M \rightsquigarrow$ parameter domain, $M \in \mathbb{N}$

- ▶ $0 < a_{\min} \leq \operatorname{ess\,inf}_{x \in D} a(x, \mathbf{y}) \leq \operatorname{ess\,sup}_{x \in D} a(x, \mathbf{y}) \leq a_{\max} < \infty$ π -a.e. on Γ

- Weak formulation: given $f \in L^2_\pi(\Gamma, L^2(D))$, find $u : \Gamma \rightarrow \mathbb{X} := H^1_0(D)$ s.t.

$$\int_D a(x, \mathbf{y}) \nabla u(x, \mathbf{y}) \cdot \nabla v(x) \, dx = \int_D f(x, \mathbf{y}) v(x) \, dx \quad \forall v \in \mathbb{X}, \pi\text{-a.e. on } \Gamma.$$

- [Babuška, Nobile, Tempone '07]: $\exists! u \in \mathbb{V} := L^2_\pi(\Gamma; \mathbb{X})$.

- Sampling the PDE inputs at a sparse grid $\mathcal{Y}_\bullet = \mathcal{Y}_{\Lambda_\bullet}$ of collocation points in Γ

Sparse grid stochastic collocation FEM

- Sampling the PDE inputs at a sparse grid $\mathcal{Y}_\bullet = \mathcal{Y}_{\Lambda_\bullet}$ of collocation points in Γ
- Solving decoupled discrete problems: for each $\mathbf{z} \in \mathcal{Y}_\bullet$, find $u_{\bullet, \mathbf{z}} \in \mathbb{X}_{\bullet, \mathbf{z}}$ satisfying

$$\int_D a(x, \mathbf{z}) \nabla u_{\bullet, \mathbf{z}}(x) \cdot \nabla v(x) dx = \int_D f(x, \mathbf{z}) v(x) dx \quad \forall v \in \mathbb{X}_{\bullet, \mathbf{z}} := \mathcal{S}_0^1(\mathcal{T}_{\bullet, \mathbf{z}}) \subset H_0^1(D)$$

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- Building a multivariable interpolant

$$u_{\bullet}^{\text{SC}}(x, \mathbf{y}) = \sum_{\mathbf{z} \in \mathcal{Y}_\bullet} u_{\bullet, \mathbf{z}}(x) L_{\bullet, \mathbf{z}}(\mathbf{y}),$$

$\{L_{\bullet, \mathbf{z}}(\mathbf{y}) : \mathbf{z} \in \mathcal{Y}_\bullet\}$ – multivariable Lagrange basis functions associated with \mathcal{Y}_\bullet

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- Main features of the stochastic collocation FEM (SC-FEM)
 - ▶ a sampling method that generates ‘surrogate approximations’
 - ▶ single-level ($\mathbb{X}_{\bullet, \mathbf{z}} = \mathbb{X}_\bullet \quad \forall \mathbf{z} \in \mathcal{Y}_\bullet$) vs. multilevel ($\mathbb{X}_{\bullet, \mathbf{z}} \neq \mathbb{X}_{\bullet, \mathbf{z}'}$ for $\mathbf{z} \neq \mathbf{z}'$)
 - ▶ not a projection method \rightsquigarrow no (global) Galerkin orthogonality

Hierarchical a posteriori error estimation in SC-FEM (1/2)

[B., Silvester, Xu '22], [B., Silvester '23]

- $\mathbb{V} := L^2_\pi(\Gamma; H^1_0(D))$, $\|\cdot\| := \|\cdot\|_{\mathbb{V}}$
- An enhanced SC-FEM approximation $\hat{u}_\bullet^{\text{SC}}$ satisfying the saturation property

$$\|u - \hat{u}_\bullet^{\text{SC}}\| \leq q_{\text{sat}} \|u - u_\bullet^{\text{SC}}\| \quad \text{with } q_{\text{sat}} \in (0, 1)$$

- This gives a **reliable** error estimate

$$\|u - u_\bullet^{\text{SC}}\| \leq (1 - q_{\text{sat}})^{-1} \|\hat{u}_\bullet^{\text{SC}} - u_\bullet^{\text{SC}}\|$$

- How to choose the enhanced approximation $\hat{u}_\bullet^{\text{SC}}$?

Hierarchical a posteriori error estimation in SC-FEM (2/2)

Recall that $u_{\bullet}^{\text{SC}}(x, \mathbf{y}) = \sum_{\mathbf{z} \in \mathcal{Y}_{\bullet}} u_{\bullet \mathbf{z}}(x) L_{\bullet \mathbf{z}}(\mathbf{y})$

$$\blacksquare \hat{u}_{\bullet}^{\text{SC}}(x, \mathbf{y}) := \underbrace{\sum_{\mathbf{z} \in \mathcal{Y}_{\bullet}} \hat{u}_{\bullet \mathbf{z}}(x) L_{\bullet \mathbf{z}}(\mathbf{y})}_{\text{spatial enhancement}} + \underbrace{\left(\sum_{\mathbf{z}' \in \hat{\mathcal{Y}}_{\bullet}} u_{0\mathbf{z}'}(x) \hat{L}_{\bullet \mathbf{z}'}(\mathbf{y}) - \sum_{\mathbf{z} \in \mathcal{Y}_{\bullet}} u_{0\mathbf{z}}(x) L_{\bullet \mathbf{z}}(\mathbf{y}) \right)}_{\text{parametric enhancement}}$$

- ▶ $\hat{u}_{\bullet \mathbf{z}} \in \hat{\mathbb{X}}_{\bullet \mathbf{z}}$ (uniform mesh-refinement) $\forall \mathbf{z} \in \mathcal{Y}_{\bullet} = \mathcal{Y}_{\Lambda_{\bullet}}$
- ▶ $\hat{\mathcal{Y}}_{\bullet} = \mathcal{Y}_{\hat{\Lambda}_{\bullet}}$ with $\hat{\Lambda}_{\bullet} := \Lambda_{\bullet} \cup \text{R}(\Lambda_{\bullet}) \rightsquigarrow \hat{\Lambda}_{\bullet}$ is monotone!
- ▶ $u_{0\mathbf{z}}(x), u_{0\mathbf{z}'}(x) \in \mathbb{X}_0 := \mathcal{S}_0^1(\mathcal{T}_0) \forall \mathbf{z} \in \mathcal{Y}_{\bullet}$ and $\forall \mathbf{z}' \in \hat{\mathcal{Y}}_{\bullet}$

Hierarchical a posteriori error estimation in SC-FEM (2/2)

Recall that $u_{\bullet}^{\text{SC}}(x, \mathbf{y}) = \sum_{z \in \mathcal{Y}_{\bullet}} u_{\bullet z}(x) L_{\bullet z}(\mathbf{y})$

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- A posteriori error estimate

$$\begin{aligned} \|u - u_{\bullet}^{\text{SC}}\| &\leq \frac{1}{1 - q_{\text{sat}}} \|\hat{u}_{\bullet}^{\text{SC}} - u_{\bullet}^{\text{SC}}\| \\ &\leq \frac{1}{1 - q_{\text{sat}}} \left(\underbrace{\left\| \sum_{z \in \mathcal{Y}_{\bullet}} (\hat{u}_{\bullet z} - u_{\bullet z}) L_{\bullet z} \right\|}_{\text{spatial estimate}} + \underbrace{\left\| \sum_{z' \in \hat{\mathcal{Y}}_{\bullet} \setminus \mathcal{Y}_{\bullet}} \left(u_{0z'} - \sum_{z \in \mathcal{Y}_{\bullet}} u_{0z} L_{\bullet z}(z') \right) \hat{L}_{\bullet z'} \right\|}_{\text{parametric estimate}} \right) \end{aligned}$$

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- Error indicators (e.g., **spatial** error indicators $\mu_{\bullet z}$)

$$\mu_{\bullet} := \left\| \sum_{z \in \mathcal{Y}_{\bullet}} (\hat{u}_{\bullet z} - u_{\bullet z}) L_{\bullet z} \right\| \leq \sum_{z \in \mathcal{Y}_{\bullet}} \|\hat{u}_{\bullet z} - u_{\bullet z}\|_{\mathbb{X}} \|L_{\bullet z}\|_{L^2_{\pi}(\Gamma)} \lesssim \sum_{z \in \mathcal{Y}_{\bullet}} \mu_{\bullet z} \|L_{\bullet z}\|_{L^2_{\pi}(\Gamma)}$$

Adaptive multilevel SC-FEM algorithm

INPUT: $\Lambda_0 = \{\mathbf{1}\}$; $\mathcal{T}_{0\mathbf{z}} := \mathcal{T}_0 \forall \mathbf{z} \in \hat{\mathcal{Y}}_0 = \mathcal{Y}_{\Lambda_0 \cup \mathbf{R}(\Lambda_0)}$; output counter k ; tolerance tol

FOR $\ell = 0, 1, 2, 3, \dots$ DO:

- SOLVE: compute $u_{\ell\mathbf{z}} \in \mathbb{X}_{\ell\mathbf{z}}$ for all $\mathbf{z} \in \hat{\mathcal{Y}}_\ell = \mathcal{Y}_{\hat{\Lambda}_\ell} = \mathcal{Y}_{\Lambda_\ell \cup \mathbf{R}(\Lambda_\ell)}$
- ESTIMATE: compute error indicators
 - ▶ spatial indicators $\mu_{\ell\mathbf{z}}$ for all $\mathbf{z} \in \mathcal{Y}_\ell$
 - ▶ parametric indicators $\tau_{\ell\nu}$ for all $\nu \in \mathbf{R}(\Lambda_\ell)$
 - ▶ If $\ell = jk, j \in \mathbb{N}$, compute the total error estimate η_ℓ and exit if $\eta_\ell < \text{tol}$
- MARK: mark certain edges/elements $\mathcal{M}_{\ell\mathbf{z}}$ ($\mathbf{z} \in \mathcal{Y}_\ell$) and indices $\Upsilon_\ell \subseteq \mathbf{R}(\Lambda_\ell)$
- REFINE: enhance approximations
 - ▶ mesh refinement (NVB) $\rightsquigarrow \mathcal{T}_{(\ell+1)\mathbf{z}} := \text{refine}(\mathcal{T}_{\ell\mathbf{z}}, \mathcal{M}_{\ell\mathbf{z}})$ for all $\mathbf{z} \in \mathcal{Y}_\ell$
 - ▶ parametric enrichment $\rightsquigarrow \Lambda_{\ell+1} := \Lambda_\ell \cup \Upsilon_\ell$ and **construct** meshes $\mathcal{T}_{(\ell+1)\mathbf{z}'}$ for **each new collocation point** \mathbf{z}'

OUTPUT: SC-FEM approximation $u_{\ell^*}^{\text{SC}}$ and the error estimate η_{ℓ^*} for some $\ell^* = jk$

- Parametric enrichment $\rightsquigarrow \Lambda_{\ell+1} := \Lambda_\ell \cup \Upsilon_\ell$

Key issue: allocation of meshes $\mathcal{T}_{(\ell+1)\mathbf{z}'}$ for each new collocation point \mathbf{z}'

Parametric enrichment

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Key issue: allocation of meshes $\mathcal{T}_{(\ell+1)\mathbf{z}'}$ for each new collocation point \mathbf{z}'

- Set $\widetilde{\text{tol}} := (\#\mathcal{Y}_\ell)^{-1} \sum_{\mathbf{z} \in \mathcal{Y}_\ell} \mu_{\ell\mathbf{z}} \|L_{(\ell+1)\mathbf{z}}\|_{L^2_\pi(\Gamma)}$

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- For **each new collocation point** \mathbf{z}'
 - ▶ Initialise the mesh $\mathcal{T}_{(\ell+1)\mathbf{z}'} := \mathcal{T}_0$
 - ▶ Iterate the standard adaptive loop

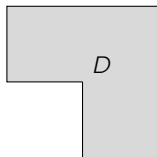
SOLVE \rightarrow ESTIMATE \rightarrow MARK \rightarrow REFINE

until the resolution of the mesh $\mathcal{T}_{(\ell+1)\mathbf{z}'}$ is such that

$$\mu_{(\ell+1)\mathbf{z}'} \|L_{(\ell+1)\mathbf{z}'}\|_{L^2_\pi(\Gamma)} < \widetilde{\text{tol}}$$

Experiment 2: nonaffine parametric coefficient

- $-\nabla \cdot (a \nabla u) = 1$ in $D \times \Gamma$, $u = 0$ on $\partial D \times \Gamma$
- $D := (-1, 1)^2 \setminus (-1, 0]^2 \rightsquigarrow$ L-shaped domain



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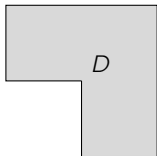
- Diffusion coefficient $a(x, \mathbf{y}) = \exp(h(x, \mathbf{y}))$

- ▶ $h(x, \mathbf{y}) = 1 + \sum_{m=1}^M \sqrt{\lambda_m} \varphi_m(x) y_m$

- ▶ $\{(\lambda_m, \varphi_m(x))\}_{m=1}^{\infty}$ are the eigenpairs of $\int_{D \cup (-1, 0]^2} \text{Cov}[h](x, x') \varphi(x') dx'$

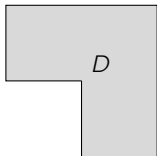
- ▶ $\text{Cov}[h](x, x') = \sigma^2 \exp(-|x_1 - x'_1| - |x_2 - x'_2|)$

- ▶ $\{y_m\}_{m \in \{1, \dots, M\}}$ are images of $U(-1, 1)$ iid mean-zero r.v., $d\pi_m(y_m) = \frac{1}{2} dy_m$



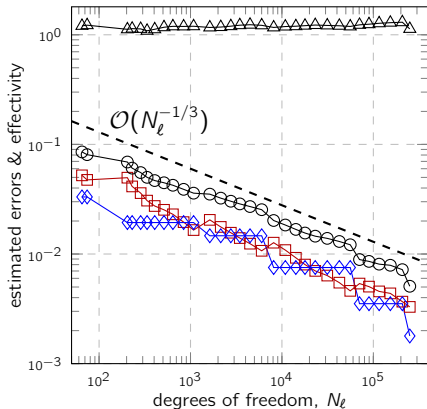
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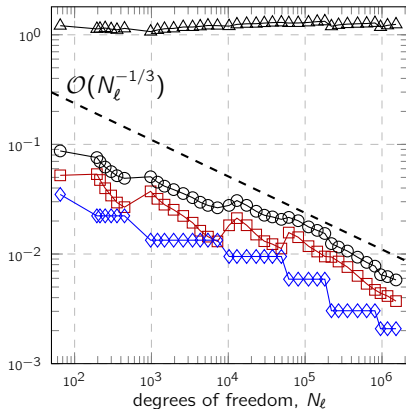


Experiment 2: effectivity and robustness of error estimates (1/2)

$M = 4 \mid \sigma = 0.5$



$M = 8 \mid \sigma = 0.5$



—□— spatial error estimates

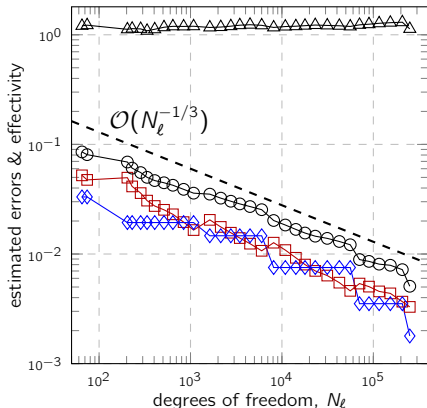
—◇— parametric error estimates

—○— total error estimates

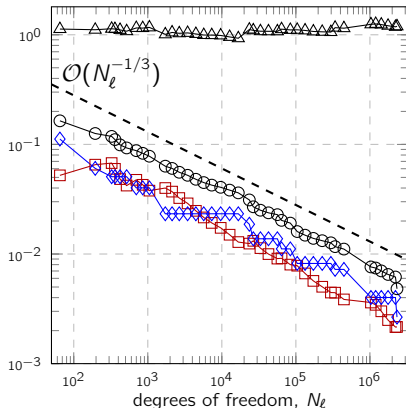
—△— effectivity indices

Experiment 2: effectivity and robustness of error estimates (2/2)

$M = 4 \mid \sigma = 0.5$



$M = 4 \mid \sigma = 1.5$



—□— spatial error estimates

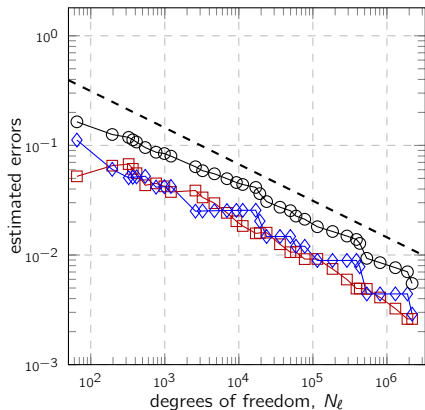
—◇— parametric error estimates

—○— total error estimates

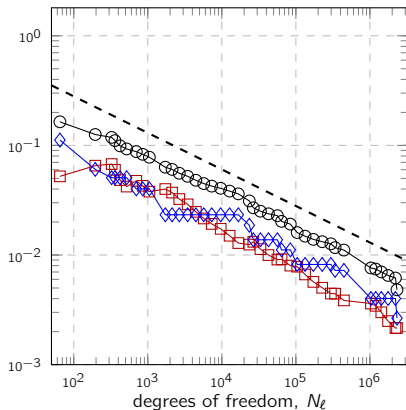
—△— effectivity indices

Experiment 2: single-level vs. multilevel refinement

single-level | $M = 4, \sigma = 1.5$



multilevel | $M = 4, \sigma = 1.5$



—□— spatial error estimates

—◇— parametric error estimates

—○— total error estimates

--- $\mathcal{O}(N_\ell^{-1/3})$

Experiment 3: one peak problem

[Kornhuber, Youett '18], [Lang, Scheichl, Silvester '20]

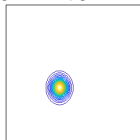
- $-\nabla^2 u = f(x, \mathbf{y})$ in $D \times \Gamma$, $u = g$ on $\partial D \times \Gamma$
- $D := (-4, 4)^2$, $\Gamma = [-1, 1]^2$, $\mathbf{y} = (y_1, y_2)$, $y_1, y_2 \sim U[-1, 1]$
- $u(x, \mathbf{y}) = \exp\left(-\frac{50}{16}\{\alpha(y_1)(x_1 - y_1)^2 + (x_2 - y_2)^2\}\right)$ with $\alpha(y_1) = (9y_1 + 11)/2$

Experiment 3: one peak problem

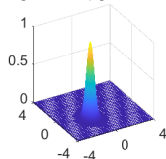
[Kornhuber, Youett '18], [Lang, Scheichl, Silvester '20]

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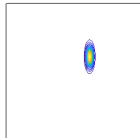
$y_1 = -0.88, y_2 = -0.88$



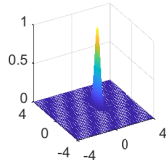
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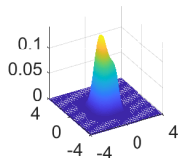
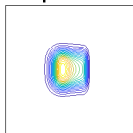


Experiment 3: one peak problem

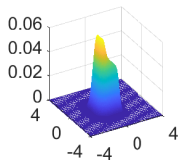
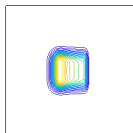
[Kornhuber, Youett '18], [Lang, Scheichl, Silvester '20]

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Expectation



Variance



Experiment 3: one peak problem

[Kornhuber, Youett '18], [Lang, Scheichl, Silvester '20]

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- Dirichlet b.c. for sampled FEM approximations: $u_{\bullet, \mathbf{z}} = 0 \quad \forall \mathbf{z} \in \mathcal{Y}_{\bullet}$
- Reference QoI

$$Q := \int_{\Gamma} \int_D (u(x, \mathbf{y}))^2 dx d\pi(\mathbf{y}) = 0.24152872 \dots$$

Experiment 3: one peak problem

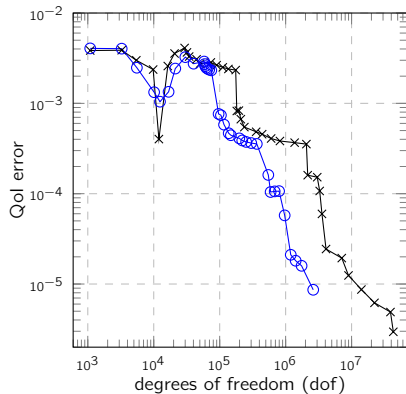
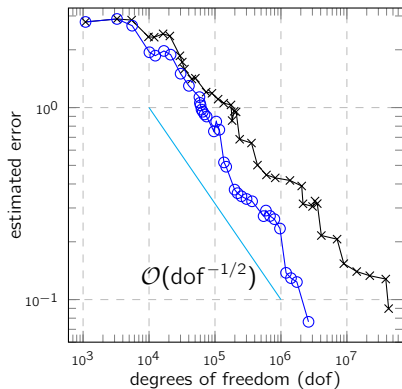
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- Adaptive stochastic collocation FEM (Clenshaw–Curtis collocation points)
 - ▶ single-level vs. multilevel refinement

Experiment 3: single-level vs. multilevel refinement (1/2)



—x— single-level

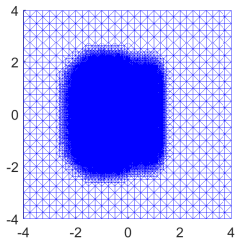
—o— multilevel

Experiment 3: single-level vs. multilevel refinement (2/2)

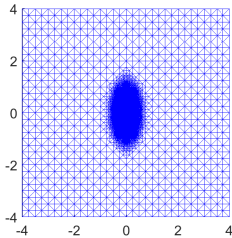
| | single-level SC-FEM | multilevel SC-FEM |
|-----------------------------|---------------------|-------------------|
| # iterations | 38 | 34 |
| # collocation points | 169 | 153 |
| final #dof | 42'961'659 | 2'620'343 |
| $ Q(u) - Q(u^{\text{SC}}) $ | 4.736e-5 | 1.381e-4 |

Experiment 3: single-level vs. multilevel refinement (2/2)

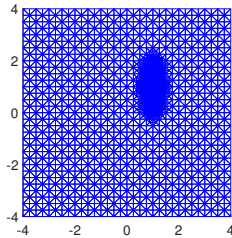
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single-level
mesh \mathcal{T}_ℓ



mesh $\mathcal{T}_{\ell z}$
 $z = (0, 0)$



mesh $\mathcal{T}_{\ell z}$
 $z = (1, 1)$

Conclusions, extensions and outlook

- For **multilevel stochastic Galerkin FEM**
 - ▶ exploiting Galerkin orthogonality & properties of orthogonal polynomials
 - ▶ novel reliable and efficient a posteriori error estimates
 - ▶ rate optimal adaptive algorithms for PDEs with *affine-parametric* inputs
 - ▶ **extensions**: goal-oriented adaptivity; parameter-dependent linear elasticity

Conclusions, extensions and outlook

- For **multilevel stochastic Galerkin FEM**
 - ▶ exploiting Galerkin orthogonality & properties of orthogonal polynomials
 - ▶ novel reliable and efficient a posteriori error estimates
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 - ▶ **extensions**: goal-oriented adaptivity; parameter-dependent linear elasticity
- For **multilevel stochastic collocation FEM**
 - ▶ reliable, effective and robust a posteriori error estimation strategy
 - ▶ applicable to problems with *affine and nonaffine* parametric inputs
 - ▶ practical error indicators for multilevel adaptivity
 - ▶ optimal convergence rates do not seem to be feasible in general
 - ▶ optimal rates can be recovered for problems with parameter-dependent local spatial features
 - ▶ **outlook**: convergence analysis, goal-oriented adaptivity, ...

■ Key references

- ▶ AB, D. Silvester, *Efficient adaptive stochastic Galerkin methods for parametric operator equations*, SIAM J. Sci. Comp., Vol. 38 (2016), pp. A2118–A2140.
- ▶ AB, D. Praetorius, L. Rocchi, M. Ruggeri, *Convergence of adaptive stochastic Galerkin FEM*, SIAM J. Numer. Anal., Vol. 57 (2019), pp. 2359–2382.
- ▶ AB, D. Praetorius, M. Ruggeri, *Two-level a posteriori error estimation for adaptive multilevel stochastic Galerkin FEM*, SIAM/ASA J. Uncertain. Quantif., Vol. 9 (2021), pp. 1184–1216.
- ▶ AB, D. Praetorius, M. Ruggeri, *Convergence and rate optimality of adaptive multilevel stochastic Galerkin FEM*, IMA J. Numer. Anal., Vol. 42 (2022), pp. 2190–2213.
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- ▶ AB, D. Silvester, *Error estimation and adaptivity for stochastic collocation finite elements. Part II: multilevel approximation*, SIAM J. Sci. Comp. (to appear).

■ Software

- ▶ Stochastic T-IFISS, https://github.com/albespalov/Stochastic_T-IFISS
- ▶ Adaptive ML-SCFEM, https://github.com/albespalov/Adaptive_ML-SCFEM