

# Hybrid high-order methods for the biharmonic problem

Alexandre Ern

ENPC and INRIA, Paris, France  
joint work with Zhaonan Dong (INRIA)

Irish Numerical Analysis Forum, 12/05/2022

- HHO for Poisson model problem
- HHO for biharmonic problem
- Numerical results
- Error analysis with low regularity

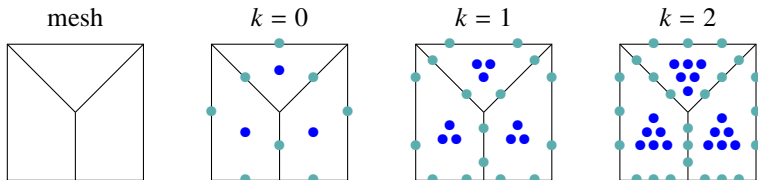
# **HHO for Poisson model problem**

# HHO methods: basic ideas

- Introduced in [Di Pietro, AE, Lemaire 14] (linear diffusion) and [Di Pietro, AE 15] (locking-free linear elasticity)
- Degrees of freedom (dofs) attached to mesh **cells** and **faces**

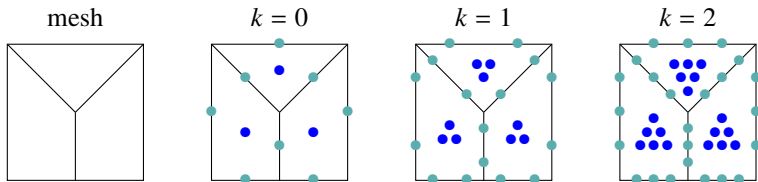
# HHO methods: basic ideas

- Introduced in [Di Pietro, AE, Lemaire 14] (linear diffusion) and [Di Pietro, AE 15] (locking-free linear elasticity)
- Degrees of freedom (dofs) attached to mesh **cells** and **faces**
- Let us start with polynomials of the **same degree  $k \geq 0$**  on **cells** and **faces** (dots do not mean point evaluation here)



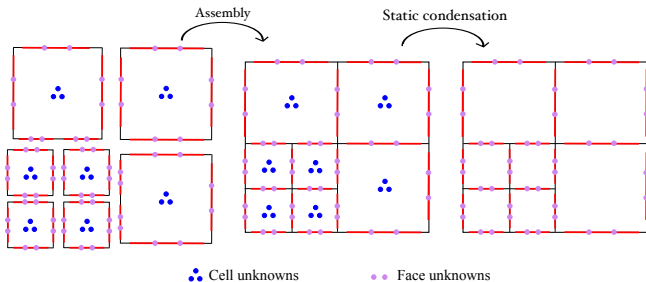
# HHO methods: basic ideas

- Introduced in [Di Pietro, AE, Lemaire 14] (linear diffusion) and [Di Pietro, AE 15] (locking-free linear elasticity)
- Degrees of freedom (dofs) attached to mesh **cells** and **faces**
- Let us start with polynomials of the **same degree  $k \geq 0$**  on **cells** and **faces** (dots do not mean point evaluation here)



- In each cell, one devises a local **gradient reconstruction** operator
- One adds **local stabilization** to weakly enforce the **matching** of **cell dof traces** with **face dofs**

# Assembly and static condensation



- Global dofs  $\hat{u}_h = (u_{\mathcal{T}}, u_{\mathcal{F}})$  ( $\mathcal{T} := \{\text{mesh cells}\}$ ,  $\mathcal{F} := \{\text{mesh faces}\}$ )

$$\hat{U}_h := \mathbb{P}^k(\mathcal{T}) \times \mathbb{P}^k(\mathcal{F}), \quad \mathbb{P}^k(\mathcal{T}) := \bigtimes_{T \in \mathcal{T}} \mathbb{P}^k(T), \quad \mathbb{P}^k(\mathcal{F}) := \bigtimes_{F \in \mathcal{F}} \mathbb{P}^k(F)$$

- Cell dofs eliminated locally by **static condensation**
  - **only face dofs are globally coupled**
  - cell dofs recovered by local post-processing
- Dirichlet conditions enforced on face boundary dofs  $\rightarrow$  subspace  $\hat{U}_{h0}$

- **General meshes:** polytopal cells, hanging nodes
- **Optimal error estimates**
  - $O(h^t)$   $H^1$ -error estimate if  $u \in H^{1+t}(\Omega)$ ,  $t \in (\frac{1}{2}, k + 1]$

face dofs of order  $k \geq 0 \implies O(h^{k+1}) H^1$ -error estimate

- duality argument for  $L^2$ -error estimate



# Main assets of HHO methods

- **General meshes:** polytopal cells, hanging nodes

- **Optimal error estimates**

- $O(h^t)$   $H^1$ -error estimate if  $u \in H^{1+t}(\Omega)$ ,  $t \in (\frac{1}{2}, k + 1]$

face dofs of order  $k \geq 0 \implies O(h^{k+1}) H^1$ -error estimate

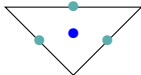
- duality argument for  $L^2$ -error estimate
- **Local conservation**
  - optimally convergent and algebraically balanced fluxes on faces
  - as any face-based method, balance at cell level
- **Attractive computational costs**
  - only face dofs are globally coupled
  - compact stencil

# Local dofs and gradient reconstruction

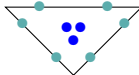
mesh cell  $T \in \mathcal{T}$



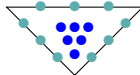
$k = 0$



$k = 1$



$k = 2$

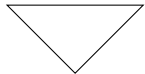


- $\hat{u}_T = (u_T, u_{\partial T})$  with cell dofs  $u_T \in \mathbb{P}^k(T)$  and face dofs  $u_{\partial T} \in \mathbb{P}^k(\mathcal{F}_{\partial T})$

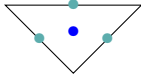
$$\hat{u}_T \in \hat{U}_T := \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}), \quad \mathbb{P}^k(\mathcal{F}_{\partial T}) := \bigtimes_{F \in \mathcal{F}_{\partial T}} \mathbb{P}^k(F)$$

# Local dofs and gradient reconstruction

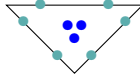
mesh cell  $T \in \mathcal{T}$



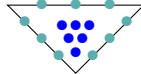
$k = 0$



$k = 1$



$k = 2$



- $\hat{u}_T = (u_T, u_{\partial T})$  with cell dofs  $u_T \in \mathbb{P}^k(T)$  and face dofs  $u_{\partial T} \in \mathbb{P}^k(\mathcal{F}_{\partial T})$

$$\hat{u}_T \in \hat{U}_T := \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}), \quad \mathbb{P}^k(\mathcal{F}_{\partial T}) := \bigtimes_{F \in \mathcal{F}_{\partial T}} \mathbb{P}^k(F)$$

- **Potential reconstruction**  $R_T : \hat{U}_T \rightarrow \mathbb{P}^{k+1}(T)$

- Main idea: mimic integration by parts (smooth functions  $u, q$ ):

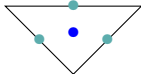
$$(\nabla u, \nabla q)_T = -(u, \Delta q)_T + (u, \nabla q \cdot \mathbf{n}_T)_{\partial T}$$

# Local dofs and gradient reconstruction

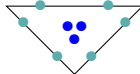
mesh cell  $T \in \mathcal{T}$



$k = 0$



$k = 1$



$k = 2$



- $\hat{u}_T = (u_T, u_{\partial T})$  with cell dofs  $u_T \in \mathbb{P}^k(T)$  and face dofs  $u_{\partial T} \in \mathbb{P}^k(\mathcal{F}_{\partial T})$

$$\hat{u}_T \in \hat{U}_T := \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}), \quad \mathbb{P}^k(\mathcal{F}_{\partial T}) := \bigtimes_{F \in \mathcal{F}_{\partial T}} \mathbb{P}^k(F)$$

- **Potential reconstruction**  $R_T : \hat{U}_T \rightarrow \mathbb{P}^{k+1}(T)$
- Main idea: mimic integration by parts (smooth functions  $u, q$ ):

$$(\nabla u, \nabla q)_T = -(u, \Delta q)_T + (u, \nabla q \cdot \mathbf{n}_T)_{\partial T}$$

- We require that  $\forall q \in \mathbb{P}^{k+1}(T)/\mathbb{P}^0$ ,

$$(\nabla R_T(\hat{u}_T), \nabla q)_T = -(u_T, \Delta q)_T + (u_{\partial T}, \nabla q \cdot \mathbf{n}_T)_{\partial T}$$

together with  $(R_T(\hat{u}_T), 1)_T = (u_T, 1)_T$

- **Gradient reconstruction**  $\mathbf{G}_T(\hat{u}_T) := \nabla R_T(\hat{u}_T) \in [\mathbb{P}^k(T)]^d$

- In all cases, the local bilinear form writes

$$a_T(\hat{u}_T, \hat{w}_T) := \underbrace{(\nabla R_T(\hat{u}_T), \nabla R_T(\hat{w}_T))_T}_{\approx (\nabla u, \nabla w)_T} + \underbrace{h_T^{-1} (S_{\partial T}(\hat{u}_T), S_{\partial T}(\hat{w}_T))_{\partial T}}_{\text{weakly enforces } u_T|_{\partial T} - u_{\partial T} \approx 0}$$

# Local stabilization and bilinear form

- In all cases, the local bilinear form writes

$$a_T(\hat{u}_T, \hat{w}_T) := \underbrace{(\nabla R_T(\hat{u}_T), \nabla R_T(\hat{w}_T))_T}_{\approx (\nabla u, \nabla w)_T} + \underbrace{h_T^{-1} (S_{\partial T}(\hat{u}_T), S_{\partial T}(\hat{w}_T))}_{\text{weakly enforces } u_T|_{\partial T} - u_{\partial T} \approx 0}$$

- Local **stabilization** operator acting on  $\delta := u_T|_{\partial T} - u_{\partial T}$

$$S_{\partial T}(\hat{u}_T) := \Pi_{\partial T}^k \left( \delta - \underbrace{((I - \Pi_T^k)R_T(0, \delta))}_{\text{high-order correction}} \right)$$

# Local stabilization and bilinear form

- In all cases, the local bilinear form writes

$$a_T(\hat{u}_T, \hat{w}_T) := \underbrace{(\nabla R_T(\hat{u}_T), \nabla R_T(\hat{w}_T))_T}_{\approx (\nabla u, \nabla w)_T} + \underbrace{h_T^{-1} (S_{\partial T}(\hat{u}_T), S_{\partial T}(\hat{w}_T))_{\partial T}}_{\text{weakly enforces } u_T|_{\partial T} - u_{\partial T} \approx 0}$$

- Local **stabilization** operator acting on  $\delta := u_T|_{\partial T} - u_{\partial T}$

$$S_{\partial T}(\hat{u}_T) := \Pi_{\partial T}^k \left( \delta - \underbrace{((I - \Pi_T^k)R_T(0, \delta))|_{\partial T}}_{\text{high-order correction}} \right)$$

- (Important) variant on cell dofs and stabilization
  - **mixed-order setting**:  $(k + 1)$  for cell dofs and  $k \geq 0$  for face dofs
  - Lehrenfeld–Schöberl HDG stabilization

$$S_{\partial T}(\hat{u}_T) := \Pi_{\partial T}^k(\delta)$$

- slightly higher cost for static condensation **compensated** by lower cost for computing stabilization

- HHO( $k = 0$ ) equivalent (up to stab.) to Hybrid FV and Hybrid Mimetic Mixed methods [Eymard, Gallouet, Herbin 10; Droniou et al. 10]



- HHO( $k = 0$ ) equivalent (up to stab.) to **Hybrid FV and Hybrid Mimetic Mixed methods** [Eymard, Gallouet, Herbin 10; Droniou et al. 10]
- HHO fits into **HDG setting** [Cockburn, Di Pietro, AE 16]
  - flux variable in HDG  $\leftrightarrow$  HHO grad. rec.
  - numerical flux trace in HHO is  $-\nabla R_T(\hat{u}_T) \cdot \mathbf{n}_T + h_T^{-1}(\tilde{S}_{\partial T}^* \circ \tilde{S}_{\partial T})(\delta)$
  - HHO allows for a **simpler** analysis based on  $L^2$ -projections: **avoids special HDG projection**

- HHO( $k = 0$ ) equivalent (up to stab.) to **Hybrid FV and Hybrid Mimetic Mixed methods** [Eymard, Gallouet, Herbin 10; Droniou et al. 10]
- HHO fits into **HDG setting** [Cockburn, Di Pietro, AE 16]
  - flux variable in HDG  $\leftrightarrow$  HHO grad. rec.
  - numerical flux trace in HHO is  $-\nabla R_T(\hat{u}_T) \cdot \mathbf{n}_T + h_T^{-1}(\tilde{S}_{\partial T}^* \circ \tilde{S}_{\partial T})(\delta)$
  - HHO allows for a **simpler** analysis based on  $L^2$ -projections: **avoids special HDG projection**
- Similar devising of HHO and **weak Galerkin** methods [Wang, Ye 13]
  - weak gradient  $\leftrightarrow$  HHO grad. rec.
  - WG often uses plain LS stabilization (**in general, suboptimal**: face dofs of order  $k \geq 0 \implies O(h^k) H^1$ -estimate)

- HHO( $k = 0$ ) equivalent (up to stab.) to **Hybrid FV and Hybrid Mimetic Mixed methods** [Eymard, Gallouet, Herbin 10; Droniou et al. 10]
- HHO fits into **HDG setting** [Cockburn, Di Pietro, AE 16]
  - flux variable in HDG  $\leftrightarrow$  HHO grad. rec.
  - numerical flux trace in HHO is  $-\nabla R_T(\hat{u}_T) \cdot \mathbf{n}_T + h_T^{-1}(\tilde{S}_{\partial T}^* \circ \tilde{S}_{\partial T})(\delta)$
  - HHO allows for a **simpler** analysis based on  $L^2$ -projections: **avoids special HDG projection**
- Similar devising of HHO and **weak Galerkin** methods [Wang, Ye 13]
  - weak gradient  $\leftrightarrow$  HHO grad. rec.
  - WG often uses plain LS stabilization (**in general, suboptimal**: face dofs of order  $k \geq 0 \implies O(h^k) H^1$ -estimate)
- HHO equivalent (up to stab.) to **ncVEM** [Ayuso, Manzini, Lipnikov 16]
  - HHO dof space  $\hat{U}_T$  isomorphic to virtual space  $\mathcal{V}_T$ 
$$\mathbb{P}^{k+1}(T) \subsetneq \mathcal{V}_T := \{v \in H^1(T) \mid \Delta v \in \mathbb{P}^k(T), \mathbf{n} \cdot \nabla v|_{\partial T} \in \mathbb{P}^k(\mathcal{F}_{\partial T})\}$$
  - see [Chaumont, AE, Lemaire, Valentin 21] for equivalence with MHM

- HHO( $k = 0$ ) equivalent (up to stab.) to **Hybrid FV and Hybrid Mimetic Mixed methods** [Eymard, Gallouet, Herbin 10; Droniou et al. 10]
- HHO fits into **HDG setting** [Cockburn, Di Pietro, AE 16]
  - flux variable in HDG  $\leftrightarrow$  HHO grad. rec.
  - numerical flux trace in HHO is  $-\nabla R_T(\hat{u}_T) \cdot \mathbf{n}_T + h_T^{-1}(\tilde{S}_{\partial T}^* \circ \tilde{S}_{\partial T})(\delta)$
  - HHO allows for a **simpler** analysis based on  $L^2$ -projections: **avoids special HDG projection**
- Similar devising of HHO and **weak Galerkin** methods [Wang, Ye 13]
  - weak gradient  $\leftrightarrow$  HHO grad. rec.
  - WG often uses plain LS stabilization (**in general, suboptimal**: face dofs of order  $k \geq 0 \implies O(h^k) H^1$ -estimate)
- HHO equivalent (up to stab.) to **ncVEM** [Ayuso, Manzini, Lipnikov 16]
  - HHO dof space  $\hat{U}_T$  isomorphic to virtual space  $\mathcal{V}_T$ 
$$\mathbb{P}^{k+1}(T) \subsetneq \mathcal{V}_T := \{v \in H^1(T) \mid \Delta v \in \mathbb{P}^k(T), \mathbf{n} \cdot \nabla v|_{\partial T} \in \mathbb{P}^k(\mathcal{F}_{\partial T})\}$$
  - see [Chaumont, AE, Lemaire, Valentin 21] for equivalence with MHM
- **Different devising viewpoints should be mutually enriching!**

- **Broad area of applications** (non-exhaustive list...)
  - **solid mechanics**: nonlinear elasticity, hyperelasticity and plasticity, contact, Tresca friction, obstacle pb
  - **fluid mechanics/porous media**: Stokes, NS, poroelasticity, fractures
  - Leray-Lions, spectral pb,  $H^{-1}$ -loads, magnetostatics, de Rham complexes

- **Broad area of applications** (non-exhaustive list...)
  - **solid mechanics**: nonlinear elasticity, hyperelasticity and plasticity, contact, Tresca friction, obstacle pb
  - **fluid mechanics/porous media**: Stokes, NS, poroelasticity, fractures
  - Leray-Lions, spectral pb,  $H^{-1}$ -loads, magnetostatics, de Rham complexes
- **Libraries**
  - industry (**code\_aster**, **code\_saturne**, EDF R&D), ongoing developments at CEA
  - academia: **diskpp (C++)** (ENPC/INRIA [github.com/wareHHouse](https://github.com/wareHHouse)), **HArD::Core** (Monash/Montpellier [github.com/jdroniou/HArDCore](https://github.com/jdroniou/HArDCore))

- **Broad area of applications** (non-exhaustive list...)
  - **solid mechanics**: nonlinear elasticity, hyperelasticity and plasticity, contact, Tresca friction, obstacle pb
  - **fluid mechanics/porous media**: Stokes, NS, poroelasticity, fractures
  - Leray-Lions, spectral pb,  $H^{-1}$ -loads, magnetostatics, de Rham complexes
- **Libraries**
  - industry (**code\_aster**, **code\_saturne**, EDF R&D), ongoing developments at CEA
  - academia: **diskpp (C++)** (ENPC/INRIA [github.com/wareHHouse](https://github.com/wareHHouse)), **HArD::Core** (Monash/Montpellier [github.com/jdroniou/HArDCore](https://github.com/jdroniou/HArDCore))
- **Textbooks**
  - **Di Pietro, Droniou**, **The HHO method for polytopal meshes. Design, analysis and applications** (Springer, 2020)
  - **Cicuttin, AE, Pignet**, **HHO methods. A primer with application to solid mechanics** (Springer Briefs, 2021)

# Main ideas in error analysis (1/3)

- Recall  $a_T(\hat{u}_T, \hat{w}_T) := (\nabla R_T(\hat{u}_T), \nabla R_T(\hat{w}_T))_T + h_T^{-1} (S_{\partial T}(\hat{u}_T), S_{\partial T}(\hat{w}_T))_{\partial T}$
- **Discrete problem:** Find  $\hat{u}_h \in \hat{U}_{h0}$  s.t.

$$a_h(\hat{u}_h, \hat{w}_h) := \sum_{T \in \mathcal{T}} a_T(\hat{u}_T, \hat{w}_T) = (f, w_{\mathcal{T}})_{\Omega}, \quad \forall \hat{w}_h \in \hat{U}_{h0}$$



# Main ideas in error analysis (1/3)

- Recall  $a_T(\hat{u}_T, \hat{w}_T) := (\nabla R_T(\hat{u}_T), \nabla R_T(\hat{w}_T))_T + h_T^{-1}(S_{\partial T}(\hat{u}_T), S_{\partial T}(\hat{w}_T))_{\partial T}$
- Discrete problem:** Find  $\hat{u}_h \in \hat{U}_{h0}$  s.t.

$$a_h(\hat{u}_h, \hat{w}_h) := \sum_{T \in \mathcal{T}} a_T(\hat{u}_T, \hat{w}_T) = (f, w_{\mathcal{T}})_{\Omega}, \quad \forall \hat{w}_h \in \hat{U}_{h0}$$

- Stability and boundedness:** There are  $0 < \alpha \leq \omega$  s.t. for all  $T \in \mathcal{T}$ ,

$$\alpha \|\hat{u}_T\|_{\hat{U}_T}^2 \leq a_T(\hat{u}_T, \hat{u}_T) \leq \omega \|\hat{u}_T\|_{\hat{U}_T}^2, \quad \forall \hat{u}_T \in \hat{U}_T$$

$$\text{with } \|\hat{u}_T\|_{\hat{U}_T}^2 := \|\nabla u_T\|_T^2 + h_T^{-1} \|u_T|_{\partial T} - u_{\partial T}\|_{\partial T}^2$$

# Main ideas in error analysis (1/3)

- Recall  $a_T(\hat{u}_T, \hat{w}_T) := (\nabla R_T(\hat{u}_T), \nabla R_T(\hat{w}_T))_T + h_T^{-1}(S_{\partial T}(\hat{u}_T), S_{\partial T}(\hat{w}_T))_{\partial T}$
- Discrete problem:** Find  $\hat{u}_h \in \hat{U}_{h0}$  s.t.

$$a_h(\hat{u}_h, \hat{w}_h) := \sum_{T \in \mathcal{T}} a_T(\hat{u}_T, \hat{w}_T) = (f, w_{\mathcal{T}})_{\Omega}, \quad \forall \hat{w}_h \in \hat{U}_{h0}$$

- Stability and boundedness:** There are  $0 < \alpha \leq \omega$  s.t. for all  $T \in \mathcal{T}$ ,

$$\alpha \|\hat{u}_T\|_{\hat{U}_T}^2 \leq a_T(\hat{u}_T, \hat{u}_T) \leq \omega \|\hat{u}_T\|_{\hat{U}_T}^2, \quad \forall \hat{u}_T \in \hat{U}_T$$

$$\text{with } \|\hat{u}_T\|_{\hat{U}_T}^2 := \|\nabla u_T\|_T^2 + h_T^{-1} \|u_T|_{\partial T} - u_{\partial T}\|_{\partial T}^2$$

- $\|\hat{u}_h\|_{\hat{U}_h}^2 := \sum_{T \in \mathcal{T}} \|\hat{u}_T\|_{\hat{U}_T}^2$  defines a **norm** on  $\hat{U}_{h0}$
- Discrete problem is well-posed (Lax–Milgram lemma)

## Main ideas in error analysis (2/3)

- Local **approximation operator**  $J_T^{\text{HHO}} : H^1(T) \rightarrow \mathbb{P}^{k+1}(T)$

$$J_T^{\text{HHO}} : H^1(T) \xrightarrow{\hat{I}_T} \hat{U}_T \xrightarrow{R_T} \mathbb{P}^{k+1}(T), \quad \hat{I}_T(v) := (\Pi_T^k(v), \Pi_{\partial T}^k(v|_{\partial T}))$$

- $J_T^{\text{HHO}}$  is the **elliptic projector** onto  $\mathbb{P}^{k+1}(T)$
- $h_T^{-\frac{1}{2}} \|S_{\partial T}(\hat{I}_T(v))\|_{\partial T} \lesssim \|\nabla(v - J_T^{\text{HHO}}(v))\|_T \lesssim h_T^{k+1} |v|_{H^{k+2}(T)}$

## Main ideas in error analysis (2/3)

- Local **approximation operator**  $J_T^{\text{HHO}} : H^1(T) \rightarrow \mathbb{P}^{k+1}(T)$

$$J_T^{\text{HHO}} : H^1(T) \xrightarrow{\hat{I}_T} \hat{U}_T \xrightarrow{R_T} \mathbb{P}^{k+1}(T), \quad \hat{I}_T(v) := (\Pi_T^k(v), \Pi_{\partial T}^k(v|_{\partial T}))$$

- $J_T^{\text{HHO}}$  is the **elliptic projector** onto  $\mathbb{P}^{k+1}(T)$
- $h_T^{-\frac{1}{2}} \|S_{\partial T}(\hat{I}_T(v))\|_{\partial T} \lesssim \|\nabla(v - J_T^{\text{HHO}}(v))\|_T \lesssim h_T^{k+1} |v|_{H^{k+2}(T)}$
- Assume exact solution  $u$  is in  $H^{1+s}(\Omega)$ ,  $s > \frac{1}{2}$
- Set  $\|v\|_{\sharp, T}^2 := \|\nabla v\|_T^2 + h_T \|\nabla v \cdot \mathbf{n}_T\|_{\partial T}^2$  and  $\|v\|_{\sharp, \mathcal{T}}^2 := \sum_{T \in \mathcal{T}} \|v\|_{\sharp, T}^2$
- The following error estimate holds:

$$\|\nabla_{\mathcal{T}}(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim \|u - J_{\mathcal{T}}^{\text{HHO}}(u)\|_{\sharp, \mathcal{T}}$$

with  $R_{\mathcal{T}}$  and  $J_{\mathcal{T}}^{\text{HHO}}$  defined cellwise using  $R_T$  and  $J_T^{\text{HHO}}$

## Main ideas in error analysis (2/3)

- Local **approximation operator**  $J_T^{\text{HHO}} : H^1(T) \rightarrow \mathbb{P}^{k+1}(T)$

$$J_T^{\text{HHO}} : H^1(T) \xrightarrow{\hat{I}_T} \hat{U}_T \xrightarrow{R_T} \mathbb{P}^{k+1}(T), \quad \hat{I}_T(v) := (\Pi_T^k(v), \Pi_{\partial T}^k(v|_{\partial T}))$$

- $J_T^{\text{HHO}}$  is the **elliptic projector** onto  $\mathbb{P}^{k+1}(T)$
- $h_T^{-\frac{1}{2}} \|S_{\partial T}(\hat{I}_T(v))\|_{\partial T} \lesssim \|\nabla(v - J_T^{\text{HHO}}(v))\|_T \lesssim h_T^{k+1} |v|_{H^{k+2}(T)}$
- Assume exact solution  $u$  is in  $H^{1+s}(\Omega)$ ,  $s > \frac{1}{2}$
- Set  $\|v\|_{\sharp, T}^2 := \|\nabla v\|_T^2 + h_T \|\nabla v \cdot \mathbf{n}_T\|_{\partial T}^2$  and  $\|v\|_{\sharp, \mathcal{T}}^2 := \sum_{T \in \mathcal{T}} \|v\|_{\sharp, T}^2$
- The following error estimate holds:

$$\|\nabla_{\mathcal{T}}(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim \|u - J_{\mathcal{T}}^{\text{HHO}}(u)\|_{\sharp, \mathcal{T}}$$

with  $R_{\mathcal{T}}$  and  $J_{\mathcal{T}}^{\text{HHO}}$  defined cellwise using  $R_T$  and  $J_T^{\text{HHO}}$

- If  $u \in H^{1+t}(\Omega)$  with  $t \in (\frac{1}{2}, k+1]$ ,  $\|\nabla_{\mathcal{T}}(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim h^t |u|_{H^{1+t}(\Omega)}$

## Main ideas in error analysis (3/3)

- **Bound on consistency error:** For all  $\hat{w}_h \in \hat{U}_{h0}$ ,

$$\begin{aligned}(f, w_{\mathcal{T}})_{\Omega} &= \sum_{T \in \mathcal{T}} (-\Delta u, w_T)_T = \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - (\nabla u \cdot \mathbf{n}_T, w_T)_{\partial T} \\ &= \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - (\nabla u \cdot \mathbf{n}_T, w_T - w_{\partial T})_{\partial T}\end{aligned}$$

Key step where **regularity assumption**  $u \in H^{1+s}(\Omega)$ ,  $s > \frac{1}{2}$ , is used

# Main ideas in error analysis (3/3)

- **Bound on consistency error:** For all  $\hat{w}_h \in \hat{U}_{h0}$ ,

$$\begin{aligned}(f, w_T)_\Omega &= \sum_{T \in \mathcal{T}} (-\Delta u, w_T)_T = \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - (\nabla u \cdot \mathbf{n}_T, w_T)_{\partial T} \\ &= \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - (\nabla u \cdot \mathbf{n}_T, w_T - w_{\partial T})_{\partial T}\end{aligned}$$

Key step where **regularity assumption**  $u \in H^{1+s}(\Omega)$ ,  $s > \frac{1}{2}$ , is used

- Recalling  $J_T^{\text{HHO}} = R_T \circ \hat{I}_T$  and definition of  $R_T(\hat{w}_T)$  gives

$$\begin{aligned}\chi(\hat{w}_h) &:= (f, w_T)_\Omega - \sum_{T \in \mathcal{T}} a_T(\hat{I}_T(u), \hat{w}_T) = (f, w_T)_\Omega - \sum_{T \in \mathcal{T}} (\nabla J_T^{\text{HHO}}(u), \nabla R_T(\hat{w}_T))_T + \text{stb.} \\ &= \sum_{T \in \mathcal{T}} (\nabla \eta, \nabla w_T)_T - (\nabla \eta \cdot \mathbf{n}_T, w_T - w_{\partial T})_{\partial T} + \text{stb.}\end{aligned}$$

with  $\eta|_T := u|_T - J_T^{\text{HHO}}(u)$ , ... so that  $|\chi(\hat{w}_h)| \lesssim \|\eta\|_{\sharp, \mathcal{T}} \|\hat{w}_h\|_{\hat{U}_h}$

# Main ideas in error analysis (3/3)

- **Bound on consistency error:** For all  $\hat{w}_h \in \hat{U}_{h0}$ ,

$$\begin{aligned}(f, w_T)_\Omega &= \sum_{T \in \mathcal{T}} (-\Delta u, w_T)_T = \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - (\nabla u \cdot \mathbf{n}_T, w_T)_{\partial T} \\ &= \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - (\nabla u \cdot \mathbf{n}_T, w_T - w_{\partial T})_{\partial T}\end{aligned}$$

Key step where **regularity assumption**  $u \in H^{1+s}(\Omega)$ ,  $s > \frac{1}{2}$ , is used

- Recalling  $J_T^{\text{HHO}} = R_T \circ \hat{I}_T$  and definition of  $R_T(\hat{w}_T)$  gives

$$\begin{aligned}\chi(\hat{w}_h) &:= (f, w_T)_\Omega - \sum_{T \in \mathcal{T}} a_T(\hat{I}_T(u), \hat{w}_T) = (f, w_T)_\Omega - \sum_{T \in \mathcal{T}} (\nabla J_T^{\text{HHO}}(u), \nabla R_T(\hat{w}_T))_T + \text{stb.} \\ &= \sum_{T \in \mathcal{T}} (\nabla \eta, \nabla w_T)_T - (\nabla \eta \cdot \mathbf{n}_T, w_T - w_{\partial T})_{\partial T} + \text{stb.}\end{aligned}$$

with  $\eta|_T := u|_T - J_T^{\text{HHO}}(u)$ , ... so that  $|\chi(\hat{w}_h)| \lesssim \|\eta\|_{\#, \mathcal{T}} \|\hat{w}_h\|_{\hat{U}_h}$

- **Regularity assumption**  $s > \frac{1}{2}$  is classical for **any nonconforming method** (CR, Nitsche, dG, HDG, ...); how to **circumvent** it?
  - modify RHS using suitable bubble functions; see [Veiser, Zanotti, 18-] for general theory and [AE, Zanotti, 20] for HHO  $\implies$  **optimal in  $H^1$**
  - keep RHS but give weaker meaning to facewise normal derivative [AE, Guermond 21 (FoCM)]  $\implies$  **allow for any  $s > 0$**



## **HHO for biharmonic problem**

- Open, bounded, polytopal Lipschitz domain  $\Omega \subset \mathbb{R}^d$ ,  $d \geq 2$
- Load  $f \in L^2(\Omega)$

$$\Delta^2 u = f \quad + \quad \text{BC's} \quad \begin{cases} u = 0, \partial_n u = 0 & \text{(type I)} \\ u = 0, \partial_{nn} u = 0 & \text{(type II)} \end{cases}$$

- Open, bounded, polytopal Lipschitz domain  $\Omega \subset \mathbb{R}^d$ ,  $d \geq 2$
- Load  $f \in L^2(\Omega)$

$$\Delta^2 u = f \quad + \quad \text{BC's} \quad \begin{cases} u = 0, \partial_n u = 0 & \text{(type I)} \\ u = 0, \partial_{nn} u = 0 & \text{(type II)} \end{cases}$$

- Focusing on type I BC's, the weak formulation is

$$\text{Find } u \in H_0^2(\Omega) \text{ s.t. } (\nabla^2 u, \nabla^2 w)_\Omega = (f, w)_\Omega \quad \forall w \in H_0^2(\Omega)$$

This problem is well-posed (Lax–Milgram lemma)

- It is also possible to consider type II BC's, non-homogeneous BC's, and mix both BC's

- Recall for **second-order PDEs** that local HHO dofs comprise
  - **cell dofs** to approximate the solution in mesh cells
  - **face dofs** to approximate the solution trace on mesh faces

$$\hat{U}_T := \mathbb{P}^{k+1}(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad \text{or} \quad \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad k \geq 0$$

- Recall for **second-order PDEs** that local HHO dofs comprise
  - **cell dofs** to approximate the solution in mesh cells
  - **face dofs** to approximate the solution trace on mesh faces

$$\hat{U}_T := \mathbb{P}^{k+1}(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad \text{or} \quad \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad k \geq 0$$

- For biharmonic problem, we need **additional face dofs**
  - either approximating the **full gradient trace** on mesh faces (vector-valued)
  - or just the **normal derivative** on mesh faces (scalar-valued)

- Recall for **second-order PDEs** that local HHO dofs comprise

- **cell dofs** to approximate the solution in mesh cells
- **face dofs** to approximate the solution trace on mesh faces

$$\hat{U}_T := \mathbb{P}^{k+1}(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad \text{or} \quad \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad k \geq 0$$

- For biharmonic problem, we need **additional face dofs**
  - either approximating the **full gradient trace** on mesh faces (vector-valued)
  - or just the **normal derivative** on mesh faces (scalar-valued)
- The choice studied in [Bonaldi, Di Pietro, Geymonat, Krasucki, 18] is

$$\hat{U}_T := \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \times [\mathbb{P}^k(\mathcal{F}_{\partial T})]^d \quad k \geq 1$$

- Recall for **second-order PDEs** that local HHO dofs comprise

- **cell dofs** to approximate the solution in mesh cells
- **face dofs** to approximate the solution trace on mesh faces

$$\hat{U}_T := \mathbb{P}^{k+1}(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad \text{or} \quad \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \quad k \geq 0$$

- For biharmonic problem, we need **additional face dofs**
  - either approximating the **full gradient trace** on mesh faces (vector-valued)
  - or just the **normal derivative** on mesh faces (scalar-valued)
- The choice studied in [Bonaldi, Di Pietro, Geymonat, Krasucki, 18] is

$$\hat{U}_T := \mathbb{P}^k(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) \times [\mathbb{P}^k(\mathcal{F}_{\partial T})]^d \quad k \geq 1$$

- We consider instead the following two alternatives, both with  $k \geq 0$

$$\hat{U}_T := \begin{cases} \mathbb{P}^{k+2}(T) \times \mathbb{P}^{k+1}(\mathcal{F}_{\partial T}) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) & d = 2 \rightarrow \text{HHO(A)} \\ \mathbb{P}^{k+2}(T) \times \mathbb{P}^{k+2}(\mathcal{F}_{\partial T}) \times \mathbb{P}^k(\mathcal{F}_{\partial T}) & d \geq 2 \rightarrow \text{HHO(B)} \end{cases}$$

- Let  $T \in \mathcal{T}$
- We want to mimic the integration by parts formula (smooth  $v, w$ ):

$$(\nabla^2 v, \nabla^2 w)_T = (v, \Delta^2 w)_T - (v, \partial_n \Delta w)_{\partial T} + (\partial_n v, \partial_{nn} w)_{\partial T} + (\partial_t v, \partial_{nt} w)_{\partial T}$$



- Let  $T \in \mathcal{T}$
- We want to mimic the integration by parts formula (smooth  $v, w$ ):

$$(\nabla^2 v, \nabla^2 w)_T = (v, \Delta^2 w)_T - (v, \partial_n \Delta w)_{\partial T} + (\partial_n v, \partial_{nn} w)_{\partial T} + (\partial_t v, \partial_{nt} w)_{\partial T}$$

- Let  $\hat{v}_T := (v_T, v_{\partial T}, \gamma_{\partial T}) \in \hat{U}_T$
- **Potential reconstruction**  $R_T : \hat{U}_T \rightarrow \mathbb{P}^{k+2}(T)$  s.t.  $\forall w \in \mathbb{P}^{k+2}(T)/\mathbb{P}^1$ ,

$$(\nabla^2 R_T(\hat{v}_T), \nabla^2 w)_T = (v_T, \Delta^2 w)_T - (v_{\partial T}, \partial_n \Delta w)_{\partial T} + (\gamma_{\partial T}, \partial_{nn} w)_{\partial T} + (\partial_t v_{\partial T}, \partial_{nt} w)_{\partial T}$$

together with  $(R_T(\hat{v}_T), \xi)_T = (v_T, \xi)_T$  for all  $\xi \in \mathbb{P}^1(T)$

- **Hessian reconstruction**  $\mathcal{H}_T(\hat{v}_T) := \nabla^2 R_T(\hat{v}_T) \in [\mathbb{P}^k(T)]^{d \times d}$

- The goal of stabilization is to weakly enforce

$$v_T|_{\partial T} \approx v_{\partial T}, \quad \partial_n v_T|_{\partial T} \approx \gamma_{\partial T}, \quad \forall \hat{v}_T := (v_T, v_{\partial T}, \gamma_{\partial T}) \in \hat{U}_T$$

- The goal of stabilization is to weakly enforce

$$v_T|_{\partial T} \approx v_{\partial T}, \quad \partial_n v_T|_{\partial T} \approx \gamma_{\partial T}, \quad \forall \hat{v}_T := (v_T, v_{\partial T}, \gamma_{\partial T}) \in \hat{U}_T$$

- For HHO(B) with  $\hat{U}_T := \mathbb{P}^{k+2}(T) \times \mathbb{P}^{k+2}(\mathcal{F}_{\partial T}) \times \mathbb{P}^k(\mathcal{F}_{\partial T})$ ,

$$S_{\partial T}(\hat{v}_T, \hat{v}_T) := h_T^{-3} \|v_T|_{\partial T} - v_{\partial T}\|_{\partial T}^2 + h_T^{-1} \|\Pi_{\partial T}^k(\partial_n v_T|_{\partial T}) - \gamma_{\partial T}\|_{\partial T}^2$$

→ natural extension of **LS stabilization** to biharmonic problem

# Local stabilization

- The goal of stabilization is to weakly enforce

$$v_T|_{\partial T} \approx v_{\partial T}, \quad \partial_n v_T|_{\partial T} \approx \gamma_{\partial T}, \quad \forall \hat{v}_T := (v_T, v_{\partial T}, \gamma_{\partial T}) \in \hat{U}_T$$

- For HHO(B) with  $\hat{U}_T := \mathbb{P}^{k+2}(T) \times \mathbb{P}^{k+2}(\mathcal{F}_{\partial T}) \times \mathbb{P}^k(\mathcal{F}_{\partial T})$ ,

$$S_{\partial T}(\hat{v}_T, \hat{v}_T) := h_T^{-3} \|v_T|_{\partial T} - v_{\partial T}\|_{\partial T}^2 + h_T^{-1} \|\Pi_{\partial T}^k(\partial_n v_T|_{\partial T}) - \gamma_{\partial T}\|_{\partial T}^2$$

→ natural extension of **LS stabilization** to biharmonic problem

- For HHO(A) with  $\hat{U}_T := \mathbb{P}^{k+2}(T) \times \mathbb{P}^{k+1}(\mathcal{F}_{\partial T}) \times \mathbb{P}^k(\mathcal{F}_{\partial T})$  and  $d = 2$

$$S_{\partial T}(\hat{v}_T, \hat{v}_T) := h_T^{-3} \|\Upsilon_{\partial T}^{k+1}(v_T|_{\partial T} - v_{\partial T})\|_{\partial T}^2 + h_T^{-1} \|\Pi_{\partial T}^k(\partial_n v_T|_{\partial T}) - \gamma_{\partial T}\|_{\partial T}^2$$

where on each face  $F \in \mathcal{F}_{\partial T}$ ,  $\Upsilon_{\partial T}^{k+1}$  matches **endpoint values and moments** on  $F$  up to degree  $(k - 1)$

- **commuting property** with tangential derivative (cf. 1D de Rham complex)
- similar operator available for any  $d \geq 2$  but maps onto  $\mathbb{P}^{k+d-1}(\mathcal{F}_{\partial T})$

- The local bilinear form writes

$$a_T(\hat{v}_T, \hat{w}_T) := (\nabla^2 R_T(\hat{v}_T), \nabla^2 R_T(\hat{w}_T))_T + S_{\partial T}(\hat{v}_T, \hat{w}_T)$$

- The local bilinear form writes

$$a_T(\hat{v}_T, \hat{w}_T) := (\nabla^2 R_T(\hat{v}_T), \nabla^2 R_T(\hat{w}_T))_T + S_{\partial T}(\hat{v}_T, \hat{w}_T)$$

- Global dofs  $\hat{v}_h := (v_{\mathcal{T}}, v_{\mathcal{F}}, \gamma_{\mathcal{F}}) \in \hat{U}_h$  with

$$\hat{U}_h := \mathbb{P}^{k+2}(\mathcal{T}) \times \mathbb{P}^{k+\delta}(\mathcal{F}) \times \mathbb{P}^k(\mathcal{F}), \quad \delta \in \{1, 2\}$$

- all faces oriented by fixed unit normal  $\mathbf{n}_F$ ,  $\gamma_F$  approximates  $\mathbf{n}_F \cdot \nabla v$
- local dofs of  $\hat{v}_h$  in a mesh cell  $T \in \mathcal{T}$ :  $(v_T, (v_F)_{F \in \mathcal{F}_{\partial T}}, ((\mathbf{n}_T \cdot \mathbf{n}_F) \gamma_F)_{F \in \mathcal{F}_{\partial T}})$

- The local bilinear form writes

$$a_T(\hat{v}_T, \hat{w}_T) := (\nabla^2 R_T(\hat{v}_T), \nabla^2 R_T(\hat{w}_T))_T + S_{\partial T}(\hat{v}_T, \hat{w}_T)$$

- Global dofs  $\hat{v}_h := (v_{\mathcal{T}}, v_{\mathcal{F}}, \gamma_{\mathcal{F}}) \in \hat{U}_h$  with

$$\hat{U}_h := \mathbb{P}^{k+2}(\mathcal{T}) \times \mathbb{P}^{k+\delta}(\mathcal{F}) \times \mathbb{P}^k(\mathcal{F}), \quad \delta \in \{1, 2\}$$

- all faces oriented by fixed unit normal  $\mathbf{n}_F$ ,  $\gamma_F$  approximates  $\mathbf{n}_F \cdot \nabla v$
- local dofs of  $\hat{v}_h$  in a mesh cell  $T \in \mathcal{T}$ :  $(v_T, (v_F)_{F \in \mathcal{F}_{\partial T}}, ((\mathbf{n}_T \cdot \mathbf{n}_F) \gamma_F)_{F \in \mathcal{F}_{\partial T}})$
- Type I BC's enforced on face boundary dofs by setting  $v_F = \gamma_F = 0$  for all  $F \subset \partial\Omega \rightarrow$  subspace  $\hat{U}_{h0}$

- **Discrete problem:** Find  $\hat{u}_h \in \hat{U}_{h0}$  s.t.

$$a_h(\hat{u}_h, \hat{w}_h) := \sum_{T \in \mathcal{T}} a_T(\hat{u}_T, \hat{w}_T) = (f, w_{\mathcal{T}})_{\Omega}, \quad \forall \hat{w}_h \in \hat{U}_{h0}$$



- **Discrete problem:** Find  $\hat{u}_h \in \hat{U}_{h0}$  s.t.

$$a_h(\hat{u}_h, \hat{w}_h) := \sum_{T \in \mathcal{T}} a_T(\hat{u}_T, \hat{w}_T) = (f, w_{\mathcal{T}})_{\Omega}, \quad \forall \hat{w}_h \in \hat{U}_{h0}$$

- Cell dofs eliminated locally by **static condensation**
  - **only face dofs are globally coupled**
  - cell dofs recovered by local post-processing

- **Discrete problem:** Find  $\hat{u}_h \in \hat{U}_{h0}$  s.t.

$$a_h(\hat{u}_h, \hat{w}_h) := \sum_{T \in \mathcal{T}} a_T(\hat{u}_T, \hat{w}_T) = (f, w_{\mathcal{T}})_{\Omega}, \quad \forall \hat{w}_h \in \hat{U}_{h0}$$

- Cell dofs eliminated locally by **static condensation**
  - **only face dofs are globally coupled**
  - cell dofs recovered by local post-processing
- Comparison of globally coupled unknowns per mesh interface
  - $d = 2$ :  $(3k + 3)$  in [Bonaldi et al., 18] vs.  $(2k + 3)$  in HHO(A)
  - $d = 3$ :  $(4k + 4)$  in [Bonaldi et al., 18] vs.  $(2k + 4)$  in HHO(B)
  - static condensation is slightly more expensive in HHO(A-B), but cost is **compensated** by simpler stabilization

- **Stability and boundedness:** There are  $0 < \alpha \leq \omega$  s.t. for all  $T \in \mathcal{T}$ ,

$$\alpha \|\hat{v}_T\|_{\hat{U}_T}^2 \leq a_T(\hat{v}_T, \hat{v}_T) \leq \omega \|\hat{v}_T\|_{\hat{U}_T}^2, \quad \forall \hat{v}_T \in \hat{U}_T$$

with  $\|\hat{v}_T\|_{\hat{U}_T}^2 := \|\nabla^2 v_T\|_T^2 + h_T^{-3} \|v_T - v_{\partial T}\|_{\partial T}^2 + h_T^{-1} \|\partial_n v_T|_{\partial T} - \gamma_{\partial T}\|_{\partial T}^2$

- **Stability and boundedness:** There are  $0 < \alpha \leq \omega$  s.t. for all  $T \in \mathcal{T}$ ,

$$\alpha \|\hat{v}_T\|_{\hat{U}_T}^2 \leq a_T(\hat{v}_T, \hat{v}_T) \leq \omega \|\hat{v}_T\|_{\hat{U}_T}^2, \quad \forall \hat{v}_T \in \hat{U}_T$$

with  $\|\hat{v}_T\|_{\hat{U}_T}^2 := \|\nabla^2 v_T\|_T^2 + h_T^{-3} \|v_T - v_{\partial T}\|_{\partial T}^2 + h_T^{-1} \|\partial_n v_T|_{\partial T} - \gamma_{\partial T}\|_{\partial T}^2$

- $\|\hat{v}_h\|_{\hat{U}_h}^2 := \sum_{T \in \mathcal{T}} \|\hat{v}_T\|_{\hat{U}_T}^2$  defines a **norm** on  $\hat{U}_{h0}$
- Discrete problem is well-posed (Lax–Milgram lemma)

- Local **approximation operator**  $J_T^{\text{HHO}} : H^2(T) \rightarrow \mathbb{P}^{k+2}(T)$

$$J_T^{\text{HHO}} : H^2(T) \xrightarrow{\hat{I}_T} \hat{U}_T \xrightarrow{R_T} \mathbb{P}^{k+2}(T)$$

$$\hat{I}_T(v) := \begin{cases} (\Pi_T^{k+2}(v), \Upsilon_{\partial T}^{k+1}(v|\partial T), \Pi_{\partial T}^k(\mathbf{n}_T \cdot \nabla v|_{\partial T})) & \text{for HHO(A)} \\ (\Pi_T^{k+2}(v), \Pi_{\partial T}^{k+2}(v|\partial T), \Pi_{\partial T}^k(\mathbf{n}_T \cdot \nabla v|_{\partial T})) & \text{for HHO(B)} \end{cases}$$

- Local **approximation operator**  $J_T^{\text{HHO}} : H^2(T) \rightarrow \mathbb{P}^{k+2}(T)$

$$J_T^{\text{HHO}} : H^2(T) \xrightarrow{\hat{I}_T} \hat{U}_T \xrightarrow{R_T} \mathbb{P}^{k+2}(T)$$

$$\hat{I}_T(v) := \begin{cases} (\Pi_T^{k+2}(v), \mathbf{Y}_{\partial T}^{k+1}(v|\partial T), \Pi_{\partial T}^k(\mathbf{n}_T \cdot \nabla v|_{\partial T})) & \text{for HHO(A)} \\ (\Pi_T^{k+2}(v), \Pi_{\partial T}^{k+2}(v|\partial T), \Pi_{\partial T}^k(\mathbf{n}_T \cdot \nabla v|_{\partial T})) & \text{for HHO(B)} \end{cases}$$

- For all  $v \in H^{2+s}(T)$ ,  $s > \frac{3}{2}$ , set

$$\|v\|_{\#,T}^2 := \|\nabla^2 v\|_T^2 + h_T^3 \|\partial_n \Delta v\|_{\partial T}^2 + h_T \|\partial_n \nabla v\|_{\partial T}^2$$

- Local **approximation operator**  $J_T^{\text{HHO}} : H^2(T) \rightarrow \mathbb{P}^{k+2}(T)$

$$J_T^{\text{HHO}} : H^2(T) \xrightarrow{\hat{I}_T} \hat{U}_T \xrightarrow{R_T} \mathbb{P}^{k+2}(T)$$

$$\hat{I}_T(v) := \begin{cases} (\Pi_T^{k+2}(v), \mathbf{\Upsilon}_{\partial T}^{k+1}(v|\partial T), \Pi_{\partial T}^k(\mathbf{n}_T \cdot \nabla v|\partial T)) & \text{for HHO(A)} \\ (\Pi_T^{k+2}(v), \Pi_{\partial T}^{k+2}(v|\partial T), \Pi_{\partial T}^k(\mathbf{n}_T \cdot \nabla v|\partial T)) & \text{for HHO(B)} \end{cases}$$

- For all  $v \in H^{2+s}(T)$ ,  $s > \frac{3}{2}$ , set

$$\|v\|_{\sharp, T}^2 := \|\nabla^2 v\|_T + h_T^3 \|\partial_n \Delta v\|_{\partial T}^2 + h_T \|\partial_n \nabla v\|_{\partial T}^2$$

- The following optimal approximation properties hold:

$$\begin{aligned} \|v - J_T^{\text{HHO}}(v)\|_{\sharp, T} &\lesssim \|v - \Pi_T^{k+2}(v)\|_{\sharp, T} \\ S_{\partial T}(\hat{I}_T(v), \hat{I}_T(v))^{\frac{1}{2}} &\lesssim \|\nabla^2(v - \Pi_T^{k+2}(v))\|_T \end{aligned}$$

Moreover, for HHO(A),  $J_T^{\text{HHO}}$  coincides with the  **$H^2$ -elliptic projector**

- Assume exact solution  $u$  is in  $H^{2+s}(\Omega)$ ,  $s > \frac{3}{2}$



- Assume exact solution  $u$  is in  $H^{2+s}(\Omega)$ ,  $s > \frac{3}{2}$
- Key step when bounding the **consistency error**: For all  $\hat{w}_h \in \hat{U}_{h0}$ ,

$$\begin{aligned}(f, w_{\mathcal{T}})_{\Omega} &= \sum_{T \in \mathcal{T}} (\Delta^2 u, w_{\mathcal{T}})_{\Omega} \\ &= \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_{\mathcal{T}})_T + (\partial_n \Delta u, w_{\mathcal{T}})_{\partial T} - (\partial_{nn} u, \partial_n w_{\mathcal{T}})_{\partial T} - (\partial_{nt} u, \partial_t w_{\mathcal{T}})_{\partial T} \\ &= \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_{\mathcal{T}})_T + (\partial_n \Delta u, w_{\mathcal{T}} - w_{\partial T})_{\partial T} - (\partial_{nn} u, \partial_n w_{\mathcal{T}} - \gamma_{\partial T})_{\partial T} - (\partial_{nt} u, \partial_t (w_{\mathcal{T}} - w_{\partial T}))_{\partial T}\end{aligned}$$

- Assume exact solution  $u$  is in  $H^{2+s}(\Omega)$ ,  $s > \frac{3}{2}$
- Key step when bounding the **consistency error**: For all  $\hat{w}_h \in \hat{U}_{h0}$ ,

$$\begin{aligned}
 (f, w_{\mathcal{T}})_{\Omega} &= \sum_{T \in \mathcal{T}} (\Delta^2 u, w_{\mathcal{T}})_{\Omega} \\
 &= \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_{\mathcal{T}})_T + (\partial_n \Delta u, w_{\mathcal{T}})_{\partial T} - (\partial_{nn} u, \partial_n w_{\mathcal{T}})_{\partial T} - (\partial_{nt} u, \partial_t w_{\mathcal{T}})_{\partial T} \\
 &= \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_{\mathcal{T}})_T + (\partial_n \Delta u, w_{\mathcal{T}} - w_{\partial T})_{\partial T} - (\partial_{nn} u, \partial_n w_{\mathcal{T}} - \gamma_{\partial T})_{\partial T} - (\partial_{nt} u, \partial_t (w_{\mathcal{T}} - w_{\partial T}))_{\partial T}
 \end{aligned}$$

- Then, letting  $\chi(\hat{w}_h) := (f, w_{\mathcal{T}})_{\Omega} - a_h(\hat{I}_{\mathcal{T}}(u), \hat{w}_h)$ , we obtain

$$|\chi(\hat{w}_h)| \lesssim \|\eta\|_{\#, \mathcal{T}} \|\hat{w}_h\|_{\hat{U}_h}, \quad \eta|_T := u|_T - J_T^{\text{HHO}}(u)$$

and  $\|\eta\|_{\#, \mathcal{T}}$  is bounded by  $\|u - \Pi_{\mathcal{T}}^{k+2}(u)\|_{\#, \mathcal{T}}$  (with  $\|\cdot\|_{\#, \mathcal{T}}^2 := \sum_{T \in \mathcal{T}} \|\cdot\|_{\#, T}^2$ )

- Recall assumption  $u \in H^{2+s}(\Omega)$ ,  $s > \frac{3}{2}$
- The following error estimate holds:

$$\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim \|u - \Pi_{\mathcal{T}}^{k+2}(u)\|_{\#, \mathcal{T}}$$

- Recall assumption  $u \in H^{2+s}(\Omega)$ ,  $s > \frac{3}{2}$
- The following error estimate holds:

$$\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim \|u - \Pi_{\mathcal{T}}^{k+2}(u)\|_{\#, \mathcal{T}}$$

- If  $k \geq 1$  and  $u \in H^{k+3}(\Omega)$ ,  $\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim h^{k+1} |u|_{H^{k+3}}$
- If  $k = 0$ ,  $\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim h(|u|_{H^3} + h^{\sigma} |u|_{H^{3+\sigma}})$ ,  $\sigma := \min(s - 1, 1)$

- Recall assumption  $u \in H^{2+s}(\Omega)$ ,  $s > \frac{3}{2}$
- The following error estimate holds:

$$\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim \|u - \Pi_{\mathcal{T}}^{k+2}(u)\|_{\#, \mathcal{T}}$$

- If  $k \geq 1$  and  $u \in H^{k+3}(\Omega)$ ,  $\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim h^{k+1} |u|_{H^{k+3}}$
- If  $k = 0$ ,  $\|\nabla_{\mathcal{T}}^2(u - R_{\mathcal{T}}(\hat{u}_h))\|_{\Omega} \lesssim h(|u|_{H^3} + h^{\sigma} |u|_{H^{3+\sigma}})$ ,  $\sigma := \min(s - 1, 1)$
- Circumventing **regularity assumption**
  - [Veese, Zanotti, 18-19] for Morley element and  $C^0$ -IPDG ( $f \in H^{-2}(\Omega)$  in 2D); extension to 3D with arbitrary degree not obvious
  - [Carstensen, Nataraj, 21] for further results on lowest-order methods
  - it is also possible to extend the techniques of [AE, Guermond, 21 (FoCM)]  
 $\implies$  allow for any  $s > 1$  (and even  $s > 0$  for type II BC's)

- Comparison with WG

- WG are designed using **suboptimal** plain least-squares stabilization
- in the table, all the methods deliver  $O(h^{k+1})$   $H^2$ -error estimate

method	cell	face	grad	$k$	ref.
WG	$k + 2$	$k + 2$	$[k + 1]^d$	$k \geq 0$	[Mu, Wang, Ye, 14]
	$k + 2$	$k + 2$	$k + 1$	$k \geq 0$	[Mu, Wang, Ye, 14]
	$k + 2$	$k + 1$	$k + 1$	$k \geq 0$	[Zhang, Zhai, 15]
	1	1	$[1]^d$	$k = 0$	[Ye, Zhang, Zhang, 20]
HHO	$k$	$k$	$[k]^d$	$k \geq 1$	[Bonaldi et al., 18]
HHO(A)	$k + 2$	$k + 1$	$k$	$k \geq 0$	present ( $d = 2$ )
HHO(B)	$k + 2$	$k + 2$	$k$	$k \geq 0$	present ( $d \geq 2$ )

- Comparison with WG

- WG are designed using **suboptimal** plain least-squares stabilization
- in the table, all the methods deliver  **$O(h^{k+1})$   $H^2$ -error estimate**

method	cell	face	grad	$k$	ref.
WG	$k + 2$	$k + 2$	$[k + 1]^d$	$k \geq 0$	[Mu, Wang, Ye, 14]
	$k + 2$	$k + 2$	$k + 1$	$k \geq 0$	[Mu, Wang, Ye, 14]
	$k + 2$	$k + 1$	$k + 1$	$k \geq 0$	[Zhang, Zhai, 15]
	1	1	$[1]^d$	$k = 0$	[Ye, Zhang, Zhang, 20]
HHO	$k$	$k$	$[k]^d$	$k \geq 1$	[Bonaldi et al., 18]
HHO(A)	$k + 2$	$k + 1$	$k$	$k \geq 0$	present ( $d = 2$ )
HHO(B)	$k + 2$	$k + 2$	$k$	$k \geq 0$	present ( $d \geq 2$ )

- Broader literature review

- $C^1$ -VEM [Brezzi, Marini, 13; Chinosi, Marini, 16; Antonietti, Manzini, Verani, 20],  $C^0$ -VEM [Zhao, Chen, Zhang, 16]
- DG [Mozolevski, Süli, 03; Georgoulis, Houston, 09],  $C^0$ -IPDG [Engel et al., 02; Brenner, Sung, 05]

- Nitsche's method and curved boundaries
  - extends ideas from [Burman, AE, 18; Burman, Cicuttin, Delay, AE, 21] on second-order (interface) problems
  - key idea: **discard integrals on  $\partial\Omega$**  when building reconstruction operator
  - boundary-penalty term needs  $O(1)$  coefficient



- Nitsche's method and curved boundaries

- extends ideas from [Burman, AE, 18; Burman, Cicuttin, Delay, AE, 21] on second-order (interface) problems
- key idea: **discard integrals on  $\partial\Omega$**  when building reconstruction operator
- boundary-penalty term needs  **$O(1)$**  coefficient

- Singular perturbation

$$-\Delta u + \varepsilon \Delta^2 u = f, \quad \varepsilon \geq 0$$

- use local cutoff function  **$\sigma_T = \max(1, \varepsilon h_T^{-2})$**  to weigh stabilization terms
- method and analysis fully robust up to  $\varepsilon = 0$

- Nitsche's method and curved boundaries

- extends ideas from [Burman, AE, 18; Burman, Cicuttin, Delay, AE, 21] on second-order (interface) problems
- key idea: **discard integrals on  $\partial\Omega$**  when building reconstruction operator
- boundary-penalty term needs  $O(1)$  coefficient

- Singular perturbation

$$-\Delta u + \varepsilon \Delta^2 u = f, \quad \varepsilon \geq 0$$

- use local cutoff function  $\sigma_T = \max(1, \varepsilon h_T^{-2})$  to weigh stabilization terms
- method and analysis fully robust up to  $\varepsilon = 0$

- $C^0$ -HHO: an extension of  $C^0$ -FEM!

- restrict to simplicial/quad/hex meshes
- local dofs related to the solution trace no longer needed

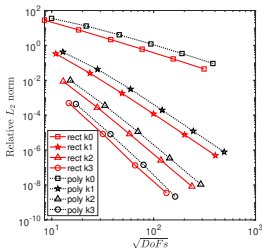
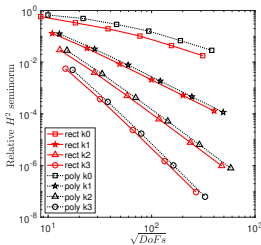
$$\hat{U}_T := \mathbb{P}^{k+2}(T) \times \mathbb{P}^k(\mathcal{F}_{\partial T})$$

- error analysis proceeds as above

## **Numerical results**

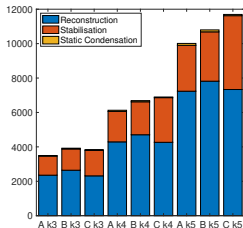
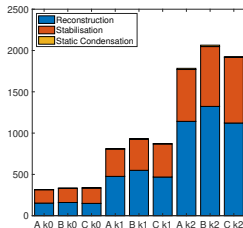
# Convergence rates

- Smooth solution  $u(x, y) = \sin(\pi x)^2 \sin(\pi y)^2$
- HHO(A),  $k \in \{0, 1, 2, 3\}$ , rectangular and polygonal (Voronoi) meshes
- Left:  $H^2$ -seminorm,  $O(h^{k+1})$
- Right:  $L^2$ -norm,  $O(h^{k+3})$  for  $k \geq 1$  and  $O(h^2)$  for  $k = 0$



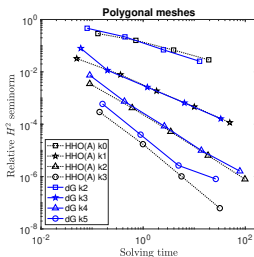
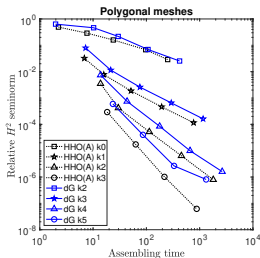
# Computational times

- Time spent on reconstruction, stabilization and static condensation
- Comparison of HHO(A), HHO(B), and HHO(C) which uses reconstruction in stabilization
- $k \in \{0, \dots, 5\}$ , polygonal mesh with 16k cells
- HHO(A) is the **most efficient** method



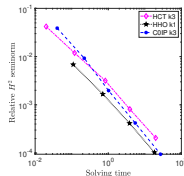
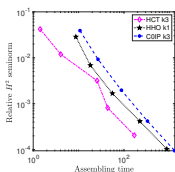
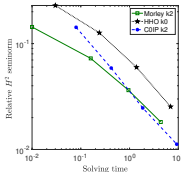
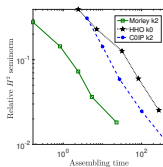
# Comparison with DG

- HHO(A) and DG on polygonal mesh (16k cells)
- $k \in \{0, 1, 2, 3\}$  for HHO(A) and  $\ell = k + 2$  for DG
- **Disclaimer:** simple Matlab implementation, no optimization
- Some (preliminary) comments
  - HHO leads to less dofs and lower assembling time than DG (cell dofs richer than face ones; numerical DG fluxes longer to evaluate)
  - solving time smaller for DG for  $k \leq 2$  and smaller for HHO if  $k \geq 3$  (HHO stencil less compact than DG stencil)



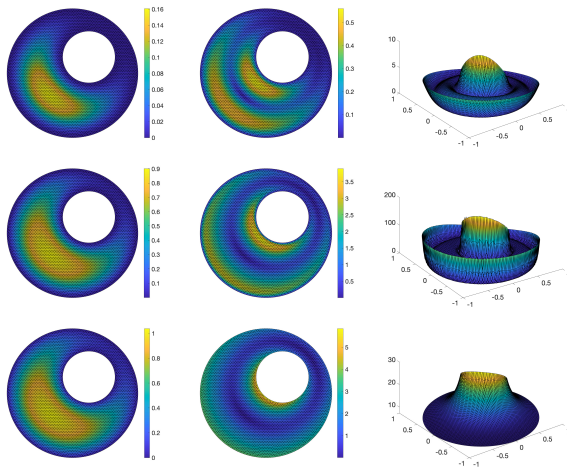
# Comparison with Morley, HCT and $C^0$ -IPDG

- Triangular meshes, finest one has 32k cells & 49k edges
- All compared methods deliver same decay rate on  $H^2$ -error
- Morley FEM more efficient than HHO( $k = 0$ )
- HCT FEM more efficient than HHO( $k = 1$ ) if assembling time is considered, but not if solving time is considered
- HHO( $k$ ) more efficient than  $C^0$ -IPDG( $k + 2$ ),  $k \in \{0, 1\}$



# Singular perturbation on curved domain

- Triangular mesh composed of 9.4k cells,  $k = 1$
- From top to bottom:  $\varepsilon = 1$ ,  $\varepsilon = 10^{-3}$ ,  $\varepsilon = 0(!)$
- From left to right: solution, gradient, Hessian (reconstructed)





## **Error analysis with low regularity**

# Localizing normal traces

- Brief summary of [AE, Guermond 21 (FoCM & *Finite Elements*, Chaps. 40-41)]
- Let  $p > 2$  and  $q \in (\frac{2d}{d+2}, 2]$
- There is  $\rho \in (2, p]$  s.t.  $q \geq \frac{\rho d}{\rho+d}$ ; let  $\rho' \in [p', 2)$  s.t.  $\frac{1}{\rho} + \frac{1}{\rho'} = 1$

# Localizing normal traces

- Brief summary of [AE, Guermond 21 (FoCM & *Finite Elements*, Chaps. 40-41)]
- Let  $p > 2$  and  $q \in (\frac{2d}{d+2}, 2]$
- There is  $\rho \in (2, p]$  s.t.  $q \geq \frac{\rho d}{\rho+d}$ ; let  $\rho' \in [p', 2)$  s.t.  $\frac{1}{\rho} + \frac{1}{\rho'} = 1$
- For all  $T \in \mathcal{T}$  and all  $F \in \mathcal{F}_{\partial T}$ , consider

$$L_F^T : W^{\frac{1}{\rho}, \rho'}(F) \xrightarrow{\text{zero extension}} W^{\frac{1}{\rho}, \rho'}(\partial T) \xrightarrow{\text{trace lifting}} W^{1, \rho'}(T)$$

# Localizing normal traces

- Brief summary of [AE, Guermond 21 (FoCM & *Finite Elements*, Chaps. 40-41)]
- Let  $p > 2$  and  $q \in (\frac{2d}{d+2}, 2]$
- There is  $\rho \in (2, p]$  s.t.  $q \geq \frac{\rho d}{\rho+d}$ ; let  $\rho' \in [p', 2)$  s.t.  $\frac{1}{\rho} + \frac{1}{\rho'} = 1$
- For all  $T \in \mathcal{T}$  and all  $F \in \mathcal{F}_{\partial T}$ , consider

$$L_F^T : W^{\frac{1}{\rho}, \rho'}(F) \xrightarrow{\text{zero extension}} W^{\frac{1}{\rho}, \rho'}(\partial T) \xrightarrow{\text{trace lifting}} W^{1, \rho'}(T)$$

- Let  $\sigma \in \mathbf{S}^d(T) := \{\tau \in \mathbf{L}^p(T); \nabla \cdot \tau \in L^q(T)\}$  ( $^d$  stands for divergence)
- Define  $\gamma_{T,F}^d(\sigma) \in (W^{\frac{1}{\rho}, \rho'}(F))'$  s.t. for all  $\phi \in W^{\frac{1}{\rho}, \rho'}(F)$ ,

$$\langle \gamma_{T,F}^d(\sigma), \phi \rangle_F := \int_T \{ \sigma \cdot \nabla L_F^T(\phi) + (\nabla \cdot \sigma) L_F^T(\phi) \}$$

If  $\sigma$  is smooth,  $\gamma_{T,F}^d(\sigma) = (\sigma \cdot \mathbf{n}_T)|_F$

## Poisson problem with DG (1/2)

- Assume  $u \in V_{\#} := \{v \in H^{1+s}(\Omega); \Delta v \in L^q(\Omega)\}$ ,  $s > 0$
- For all  $v \in V_{\#}$ ,  $\nabla v \in \mathbf{H}^s(\Omega) \hookrightarrow \mathbf{L}^p(\Omega)$ ,  $p > 2$ ; hence,

$$\nabla v \in \mathbf{S}^d(\Omega) := \{\sigma \in \mathbf{L}^p(\Omega); \nabla \cdot \sigma \in L^q(\Omega)\}$$

## Poisson problem with DG (1/2)

- Assume  $u \in V_{\#} := \{v \in H^{1+s}(\Omega); \Delta v \in L^q(\Omega)\}$ ,  $s > 0$
- For all  $v \in V_{\#}$ ,  $\nabla v \in \mathbf{H}^s(\Omega) \hookrightarrow \mathbf{L}^p(\Omega)$ ,  $p > 2$ ; hence,

$$\nabla v \in \mathbf{S}^d(\Omega) := \{\sigma \in \mathbf{L}^p(\Omega); \nabla \cdot \sigma \in L^q(\Omega)\}$$

- Bilinear form on  $(V_{\#} + \mathbb{P}^k(\mathcal{T})) \times \mathbb{P}^k(\mathcal{T})$

$$n_{\#}^{(2)}(v, w_{\mathcal{T}}) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla v), w_T|_F - \{w_{\mathcal{T}}\}_F \rangle_F$$

Notice that  $n_{\#}^{(2)}(v_{\mathcal{T}}, w_{\mathcal{T}}) = \sum_{F \in \mathcal{F}} \int_F \{\nabla v_{\mathcal{T}}\}_F \cdot \mathbf{n}_F \llbracket w_{\mathcal{T}} \rrbracket_F$  if  $v_{\mathcal{T}} \in \mathbb{P}^k(\mathcal{T})$

# Poisson problem with DG (1/2)

- Assume  $u \in V_{\#} := \{v \in H^{1+s}(\Omega); \Delta v \in L^q(\Omega)\}$ ,  $s > 0$
- For all  $v \in V_{\#}$ ,  $\nabla v \in \mathbf{H}^s(\Omega) \hookrightarrow \mathbf{L}^p(\Omega)$ ,  $p > 2$ ; hence,

$$\nabla v \in \mathbf{S}^d(\Omega) := \{\sigma \in \mathbf{L}^p(\Omega); \nabla \cdot \sigma \in L^q(\Omega)\}$$

- Bilinear form on  $(V_{\#} + \mathbb{P}^k(\mathcal{T})) \times \mathbb{P}^k(\mathcal{T})$

$$n_{\#}^{(2)}(v, w_{\mathcal{T}}) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla v), w_T|_F - \{w_{\mathcal{T}}\}_F \rangle_F$$

Notice that  $n_{\#}^{(2)}(v_{\mathcal{T}}, w_{\mathcal{T}}) = \sum_{F \in \mathcal{F}} \int_F \{\nabla v_{\mathcal{T}}\}_F \cdot \mathbf{n}_F \llbracket w_{\mathcal{T}} \rrbracket_F$  if  $v_{\mathcal{T}} \in \mathbb{P}^k(\mathcal{T})$

- Using **commuting mollification operators**, one proves that for all  $v \in V_{\#}$ ,

$$n_{\#}^{(2)}(v, w_{\mathcal{T}}) = \sum_{T \in \mathcal{T}} (\nabla v, \nabla w_T)_T + (\Delta v, w_T)_T$$

This property essentially appears as an **assumption** in the medium analysis [Gudi, 10]

- Consider interior penalty DG (IPDG) [Arnold, 82]
- The **key relation** for consistency is

$$(f, w_{\mathcal{T}})_{\Omega} = \sum_{T \in \mathcal{T}} (-\Delta u, w_T)_T = \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - n_{\#}^{(2)}(u, w_{\mathcal{T}})$$



## Poisson problem with DG (2/2)

- Consider interior penalty DG (IPDG) [Arnold, 82]
- The **key relation** for consistency is

$$(f, w_{\mathcal{T}})_{\Omega} = \sum_{T \in \mathcal{T}} (-\Delta u, w_T)_T = \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - n_{\#}^{(2)}(u, w_{\mathcal{T}})$$

- For IPDG,  $a_{\mathcal{T}}^{\text{DG}}(v_{\mathcal{T}}, w_{\mathcal{T}}) = \sum_{T \in \mathcal{T}} (\nabla v_T, \nabla w_T)_T - n_{\#}^{(2)}(v_{\mathcal{T}}, w_{\mathcal{T}}) + \text{stb.}$

## Poisson problem with DG (2/2)

- Consider interior penalty DG (IPDG) [Arnold, 82]
- The **key relation** for consistency is

$$(f, w_{\mathcal{T}})_{\Omega} = \sum_{T \in \mathcal{T}} (-\Delta u, w_T)_T = \sum_{T \in \mathcal{T}} (\nabla u, \nabla w_T)_T - n_{\#}^{(2)}(u, w_{\mathcal{T}})$$

- For IPDG,  $a_{\mathcal{T}}^{\text{DG}}(v_{\mathcal{T}}, w_{\mathcal{T}}) = \sum_{T \in \mathcal{T}} (\nabla v_T, \nabla w_T)_T - n_{\#}^{(2)}(v_{\mathcal{T}}, w_{\mathcal{T}}) + \text{stb.}$
- Letting  $\eta := u - \Pi_{\mathcal{T}}^k(u)$ , the consistency error is bounded as follows:

$$\begin{aligned} \chi(w_{\mathcal{T}}) &:= (f, w_{\mathcal{T}})_{\Omega} - a_{\mathcal{T}}^{\text{DG}}(\Pi_{\mathcal{T}}^k(u), w_{\mathcal{T}}) \\ &= \sum_{T \in \mathcal{T}} (\nabla \eta, \nabla w_T)_T - n_{\#}^{(2)}(\eta, w_{\mathcal{T}}) + \text{stb.} \end{aligned}$$

Conclude with boundedness property  $|n_{\#}^{(2)}(\eta, w_{\mathcal{T}})| \lesssim \|\eta\|_{\#, \mathcal{T}} \|w_{\mathcal{T}}\|_h$

- Exploiting the face variable representing the trace, we define the following bilinear form on  $(V_{\#} + \mathbb{P}^{k+1}(\mathcal{T})) \times \hat{U}_{h0}$ :

$$\hat{n}_{\#}^{(2)}(v, \hat{w}_h) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla v), w_T|_F - w_{\partial T}|_F \rangle_F$$

# Adaptation to HHO

- Exploiting the face variable representing the trace, we define the following bilinear form on  $(V_{\#} + \mathbb{P}^{k+1}(\mathcal{T})) \times \hat{U}_{h0}$ :

$$\hat{n}_{\#}^{(2)}(v, \hat{w}_h) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla v), w_T|_F - w_{\partial T}|_F \rangle_F$$

- The first key relation is  $\hat{n}_{\#}^{(2)}(v, \hat{w}_h) = n_{\#}^{(2)}(v, w_{\mathcal{T}})$  for all  $v \in V_{\#}$

- Exploiting the face variable representing the trace, we define the following bilinear form on  $(V_{\#} + \mathbb{P}^{k+1}(\mathcal{T})) \times \hat{U}_{h0}$ :

$$\hat{n}_{\#}^{(2)}(v, \hat{w}_h) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla v), w_T|_F - w_{\partial T}|_F \rangle_F$$

- The first key relation is  $\hat{n}_{\#}^{(2)}(v, \hat{w}_h) = n_{\#}^{(2)}(v, w_{\mathcal{T}})$  for all  $v \in V_{\#}$
- The link to the **reconstruction operator** is as follows:

$$\begin{aligned} a_h(\hat{I}_{\mathcal{T}}(u), \hat{w}_h) &= \sum_{T \in \mathcal{T}} (\nabla J_T^{\text{HHO}}(u), \nabla R_T(\hat{w}_T))_T + \text{stb.} \\ &= \sum_{T \in \mathcal{T}} (\nabla J_T^{\text{HHO}}(u), \nabla w_T)_T - \hat{n}_{\#}^{(2)}(J_{\mathcal{T}}^{\text{HHO}}(u), \hat{w}_h) + \text{stb.} \end{aligned}$$

- Exploiting the face variable representing the trace, we define the following bilinear form on  $(V_{\#} + \mathbb{P}^{k+1}(\mathcal{T})) \times \hat{U}_{h0}$ :

$$\hat{n}_{\#}^{(2)}(v, \hat{w}_h) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla v), w_T|_F - w_{\partial T}|_F \rangle_F$$

- The first key relation is  $\hat{n}_{\#}^{(2)}(v, \hat{w}_h) = n_{\#}^{(2)}(v, w_{\mathcal{T}})$  for all  $v \in V_{\#}$
- The link to the **reconstruction operator** is as follows:

$$\begin{aligned} a_h(\hat{I}_{\mathcal{T}}(u), \hat{w}_h) &= \sum_{T \in \mathcal{T}} (\nabla J_T^{\text{HHO}}(u), \nabla R_T(\hat{w}_T))_T + \text{stb.} \\ &= \sum_{T \in \mathcal{T}} (\nabla J_T^{\text{HHO}}(u), \nabla w_T)_T - \hat{n}_{\#}^{(2)}(J_{\mathcal{T}}^{\text{HHO}}(u), \hat{w}_h) + \text{stb.} \end{aligned}$$

- Letting  $\eta := u - J_{\mathcal{T}}^{\text{HHO}}(u)$ , we recover

$$\chi(\hat{w}_h) = \sum_{T \in \mathcal{T}} (\nabla \eta, w_T)_T - \hat{n}_{\#}^{(2)}(\eta, \hat{w}_h) + \text{stb.}$$

- Above technique extends to IPDG/HHO for biharmonic problem
- The critical step is to give a meaning to  $\partial_n \Delta v$  on mesh faces

- Above technique extends to IPDG/HHO for biharmonic problem
- The critical step is to give a meaning to  $\partial_n \Delta v$  on mesh faces
- If  $u \in H^{3+s}(\Omega)$ ,  $s > 0$ , and  $f \in L^q(\Omega)$ ,  $q \in (\frac{2d}{2+d}, 2]$ , then

$$\sigma := \nabla \Delta u \in \mathbf{S}^d(\Omega)$$

$\implies \gamma_{T,F}^d(\sigma)$  is well defined on all the mesh faces



- In this setting, we can lower the regularity even further

$$u \in H^{2+s}(\Omega), \quad s > 0, \quad f \in H^{-1}(\Omega)$$

With type II BC's, one has  $\Delta u \in H_0^1(\Omega) \implies \nabla \Delta u \in \mathbf{L}^2(\Omega)$ !

- In this setting, we can lower the regularity even further

$$u \in H^{2+s}(\Omega), \quad s > 0, \quad f \in H^{-1}(\Omega)$$

With type II BC's, one has  $\Delta u \in H_0^1(\Omega) \implies \nabla \Delta u \in \mathbf{L}^2(\Omega)$ !

- Let us set  $V_{\#} := \{v \in H^{2+s}(\Omega); \Delta v \in H_0^1(\Omega)\}$
- In  $C^0$ -HHO, the cell dofs are in  $\mathbb{P}^{g,k}(\mathcal{T}) := \mathbb{P}^k(\mathcal{T}) \cap H_0^1(\Omega)$

- In this setting, we can lower the regularity even further

$$u \in H^{2+s}(\Omega), \quad s > 0, \quad f \in H^{-1}(\Omega)$$

With type II BC's, one has  $\Delta u \in H_0^1(\Omega) \implies \nabla \Delta u \in \mathbf{L}^2(\Omega)$ !

- Let us set  $V_{\#} := \{v \in H^{2+s}(\Omega); \Delta v \in H_0^1(\Omega)\}$
- In  $C^0$ -HHO, the cell dofs are in  $\mathbb{P}^{g,k}(\mathcal{T}) := \mathbb{P}^k(\mathcal{T}) \cap H_0^1(\Omega)$
- We consider on  $(V_{\#} \times \mathbb{P}^{g,k}(\mathcal{T})) \times \mathbb{P}^{g,k}(\mathcal{T})$  the bilinear form

$$n_{\#}^{(4)}(v, w_{\mathcal{T}}) := \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \sum_{i \in \{1:d\}} \langle \gamma_{T,F}^d(\nabla \partial_i v), \mathbf{n}_{T,i}(\partial_n w_T - \mathbf{n}_{T \cdot} \{ \nabla w_{\mathcal{T}} \}_F) |_F \rangle_F$$

Notice that  $\nabla \partial_i v \in \mathbf{S}^d(\Omega)$  for all  $i \in \{1:d\}$  (with  $q = 2$ )

## $C^0$ -methods with type II BC's (2/2)

- The **key relation** for consistency in  $C^0$ -IPDG is

$$\langle \Delta^2 u, w_{\mathcal{T}} \rangle_{H^{-1}, H_0^1} = \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_T)_T - n_{\#}^{(4)}(u, w_{\mathcal{T}})$$

## $C^0$ -methods with type II BC's (2/2)

- The **key relation** for consistency in  $C^0$ -IPDG is

$$\langle \Delta^2 u, w_{\mathcal{T}} \rangle_{H^{-1}, H_0^1} = \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_T)_T - n_{\#}^{(4)}(u, w_{\mathcal{T}})$$

- For  $C^0$ -HHO, one exploits the presence of the face variable representing the normal derivative by setting

$$\hat{n}_{\#}^{(4)}(v, \hat{w}_h) := \sum_{i \in \{1:d\}} \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla \partial_i v), \mathbf{n}_{T,i}(\partial_n w_T - \chi_{\partial T})|_F \rangle_F$$

## $C^0$ -methods with type II BC's (2/2)

- The **key relation** for consistency in  $C^0$ -IPDG is

$$\langle \Delta^2 u, w_{\mathcal{T}} \rangle_{H^{-1}, H_0^1} = \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_T)_T - \hat{n}_{\#}^{(4)}(u, w_{\mathcal{T}})$$

- For  $C^0$ -HHO, one exploits the presence of the face variable representing the normal derivative by setting

$$\hat{n}_{\#}^{(4)}(v, \hat{w}_h) := \sum_{i \in \{1:d\}} \sum_{T \in \mathcal{T}} \sum_{F \in \mathcal{F}_{\partial T}} \langle \gamma_{T,F}^d(\nabla \partial_i v), \mathbf{n}_{T,i}(\partial_n w_T - \chi_{\partial T})|_F \rangle_F$$

- The link to the **reconstruction operator** is as follows:

$$a_h(\hat{I}_{\mathcal{T}}(u), \hat{w}_h) = \sum_{T \in \mathcal{T}} (\nabla^2 J_T^{\text{HHO}}(u), \nabla^2 w_T)_T - \hat{n}_{\#}^{(4)}(J_{\mathcal{T}}^{\text{HHO}}(u), \hat{w}_h) + \text{stb.}$$

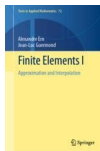
Moreover,

$$\langle \Delta^2 u, w_{\mathcal{T}} \rangle_{H^{-1}, H_0^1} = \sum_{T \in \mathcal{T}} (\nabla^2 u, \nabla^2 w_T)_T - \hat{n}_{\#}^{(4)}(u, \hat{w}_h)$$

# Some references

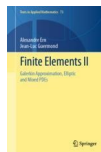
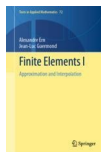
- HHO
  - [Di Pietro, AE, Lemaire 14 (CMAM); Di Pietro, AE 15 (CMAME)]
- HHO for biharmonic problem
  - [Bonaldi et al. 18 (M2AN)]
  - [Dong & AE 21 (hal-03185683); 21 (M2AN)]
- Error analysis with low regularity [AE, Guermond 21 (FoCM)]

- HHO
  - [Di Pietro, AE, Lemaire 14 (CMAM); Di Pietro, AE 15 (CMAME)]
- HHO for biharmonic problem
  - [Bonaldi et al. 18 (M2AN)]
  - [Dong & AE 21 (hal-03185683); 21 (M2AN)]
- Error analysis with low regularity [AE, Guermond 21 (FoCM)]
- **Recent Finite Element book(s)** (Springer, TAM vols. 72-74, 2021)  
with J.-L. Guermond, 83 chapters of 12/14 pages plus about 500 exercises





- HHO
  - [Di Pietro, AE, Lemaire 14 (CMAM); Di Pietro, AE 15 (CMAME)]
- HHO for biharmonic problem
  - [Bonaldi et al. 18 (M2AN)]
  - [Dong & AE 21 (hal-03185683); 21 (M2AN)]
- Error analysis with low regularity [AE, Guermond 21 (FoCM)]
- **Recent Finite Element book(s)** (Springer, TAM vols. 72-74, 2021)  
with J.-L. Guermond, 83 chapters of 12/14 pages plus about 500 exercises



Thank you for your attention!